

# **GUIDELINES FOR SEISMIC DESIGN OF TALL BUILDINGS**

Developed by the

**Pacific Earthquake Engineering Research Center**

Under its

**Tall Buildings Initiative**

March 21, 2009

## **GUIDELINES FOR SEISMIC DESIGN OF TALL BUILDINGS**

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## Glossary

**Capacity Design** – a design approach in which those portions of the structure anticipated to experience inelastic behavior in response to strong shaking are identified and detailed to reliably exhibit such behavior, while other portions of the structure are designed with sufficient strength to remain essentially elastic during earthquake response.

**Capping Strength** – the peak strength attained by a structural component under monotonic loading

**Design Earthquake Shaking** – ground shaking having an intensity represented by an elastic response spectrum that has 2/3 of the amplitude of the Maximum Considered Earthquake shaking spectrum.

**Expected Strength** – the probable actual, as opposed to minimum or specified strength of structural elements considering variability in material strength and strain hardening.

**Hazard Curve** – a plot of the probability of exceedance within a fixed number of years (often 50) of a ground motion intensity parameter as a function of the ground motion intensity parameter.

**Hazard Level** – a probability of exceedance within a defined time period (or a return period) at which ground shaking intensity is quantified

**Lower-bound Strength** – the probable minimum strength that a structural element might have, considering potential variability in material strength and workmanship.

**Maximum Considered Earthquake Shaking** – the most severe level of shaking that ordinary occupancy buildings designed in accordance with ASCE 7.05 are intended to resist without significant risk of collapse.

**Return Period** – The average number of years between repeat occurrence of events having an intensity that is equal to or greater than a specific value.

**Service Level Earthquake Shaking** – shaking, as represented by an elastic acceleration response spectrum that has a mean return period of 25 years, approximately equivalent to a 90% probability of exceedance in 50 years.

**Site Response Analysis** - analysis of wave propagation through a nonlinear soil medium

**Uniform Hazard Spectrum** – a site-specific acceleration response spectrum constructed such that each ordinate has the same exceedance probability or average return period.

## Notation

$C_d$	a deflection amplification coefficient specified by the building code
$D$	the effects of the structure's self weight and permanently attached equipment and fixtures
$E_x$	earthquake effects, including displacement, force, drift, strain, etc., resulting from earthquake shaking applied in one principal axis of building response
$E_y$	earthquake effects, including displacement, force, drift, strain, etc., resulting from earthquake shaking applied along an axis that is orthogonal to the x axis
$F_c$	Peak (capping) strength of an element under monotonic loading
$F_{n,e}$	Nominal strength computed using applicable material standard strength formulations, but using expected material strength rather than nominal or specified strength
$F_r$	Post-peak residual yield strength under monotonic loading
$F_y$	Effective yield strength of a component under monotonic loading
$F_u$	Strength demand from a suite of nonlinear response history analyses used to evaluate the adequacy of components with brittle failure modes
$IM$	A ground motion intensity measure such as peak ground acceleration, spectral response acceleration at a particular period, etc.
$K_e$	effective elastic stiffness
$K_p$	effective post-yield stiffness under monotonic loading
$K_{pc}$	effective post-peak strength stiffness under monotonic loading
$L$	the design or maximum "point in time" live load (without reduction) per the building code
$L_{exp}$	that portion of the design live load expected to be present at the time of a severe earthquake event
$M$	earthquake magnitude
$R$	distance of a site from an earthquake source
$R$	response modification coefficient specified by the building code
$u_{FM}$	ground motion at a building's base mat
$u_g$	ground motion in the free field at the ground surface



$\varepsilon$	the number of standard deviations above (+) or below (-) a value lies below the mean value for the population
$\delta_c$	deformation at which peak strength of an element is attained, under monotonic loading
$\delta_p$	plastic deformation available under monotonic loading from effective yield ( $\delta_y$ ) to attainment of peak strength ( $\delta_c$ )
$\delta_{pc}$	post-peak strength component deformation available under monotonic loading, prior to failure
$\delta_u$	ultimate deformation
$\delta_y$	component yield deformation
$\kappa$	ratio of post-peak residual yield strength to initial yield strength under monotonic loading
$\phi$	resistance factor, as obtained from appropriate material standard
$\Omega_o$	an overstrength factor specified by the building code
$\sigma$	the standard deviation of a population of values
$\mu$	the mean value of a population of values

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## 1 Introduction

### 1.1 Purpose

Structural and geotechnical engineers and researchers associated with the Pacific Earthquake Engineering Research Center developed these *Guidelines for Seismic Design of Tall Buildings* as a recommended alternative to the prescriptive procedures for seismic design of buildings contained in *ASCE 7.05* and other standards incorporated by reference into the *International Building Code*. These guidelines may be used as:

- A basis for the seismic design of individual tall buildings under the alternative means provisions of the building code;
- A basis for development and adoption of future building code provisions governing the design of tall buildings.

The recommendations presented herein are intended, if appropriately applied and executed, to result in buildings that are capable of more reliably achieving the intended performance objectives for Occupancy Category II buildings under the building code. Individual users may adapt and modify these recommendations to serve as the basis for design intended to provide superior performance to that desired for Occupancy Category II buildings.

These Guidelines are intended to serve as a reference source for design engineers, building officials, peer reviewers, and developers of building codes and standards.

### 1.2 Scope

The design recommendations contained herein are intended for application to the seismic design of tall building structures. Rather than setting a specific height limit for their applicability, as is done with certain structural systems in the building code, these guidelines apply to the seismic design of structures that generally have the characteristics that render the seismic response of tall buildings unique. These characteristics include all of the following:

- A fundamental translational period of vibration significantly in excess of 1 second
- Significant mass participation and lateral response in higher modes of vibration
- A slender aspect ratio of the seismic-force-resisting system such that significant portions of the lateral drift result from axial deformation of the walls, columns, or both, as opposed to shearing deformation of the frames or walls.

These guidelines were developed as an alternative means of compliance with the building code requirements for structural resistance to seismic loads considering the seismic hazard in the Western United States and for structures that are designed to resist strong earthquake motion through inelastic response of the structural components. The recommendations presented herein may be applicable to the design of structures that do not exhibit substantial inelastic response and that are located in regions with

seismicity somewhat different than in the Western United States, however, some modification may be appropriate. They are intended to apply to buildings in Occupancy Category II as defined in Table 1-1 of ASCE 7.05.

Structural design for other than seismic resistance and design of nonstructural components and systems for seismic resistance are not within the scope of this document. Such design should conform to the requirements of the applicable building code or other suitable alternatives.

### 1.3 Design Considerations

In recent years, a number of tall buildings have been designed and constructed in the Western United States using seismic-force-resisting systems that do not strictly comply with the prescriptive requirements of the building codes in effect at the time of their design. In some cases, these structures generally complied with the applicable building code criteria, except that the height limit specified by the building code for the selected seismic-force-resisting system was exceeded, while in other cases, seismic force-resistance was provided by structural systems that were not covered by the building code.

The seismic design of these buildings was developed using performance-based procedures in which the engineer proportioned the building for intended nonlinear response and then used nonlinear structural analysis to verify that the structure's performance would be acceptable when subjected to severe ground shaking. Building permits for these buildings have generally been issued under Section 104 of the building code. Section 104 permits the use of alternative means and methods of design and construction, provided that the building official finds that such design and construction results in a building with equivalent performance capability to that anticipated for buildings that strictly comply with the code criteria. This same approach is adopted by these guidelines.

Seismic design of tall buildings in accordance with these guidelines can offer a number of advantages including:

- More reliable attainment of intended seismic performance
- Reduced construction cost
- Accommodation of architectural features that may not otherwise be attainable
- Use of innovative structural systems and materials

Notwithstanding the above, building design using these procedures should not be undertaken without due consideration of the following:

- Appropriate implementation of these guidelines requires extensive knowledge of ground shaking hazards, structural materials behavior and nonlinear dynamic structural response and analysis. Engineers not possessing the necessary knowledge or skills should not undertake design in accordance with these

guidelines.

- Seismic response of structures designed in accordance with these criteria may place extensive nonlinear cyclic strains on structural elements. In order to reliably withstand such strains, structures must be constructed to exacting quality control standards. These guidelines should not be used where contractors and inspectors lack the necessary skills and knowledge to appropriately execute these designs.
- Acceptance of designs conducted in accordance with these procedures is at the discretion of the building official, as outlined under Section 104 of the building code. Each building official can and some building officials have declined to accept these procedures. Prior to initiating a design under the criteria presented herein, development teams should ascertain that this approach will be acceptable to the authority having jurisdiction.
- The design and permitting process for a building designed in accordance with these guidelines will generally entail greater effort and take more time than designs that strictly conform to the building code prescriptive criteria.
- Even in communities where the authority having jurisdiction is willing to accept alternative designs, the development team bears a risk that the authority having jurisdiction will ultimately decide that the design is not acceptable without incorporation of structural features that may make the project undesirable from cost or other perspectives.
- In the event that a building designed in accordance with these guidelines is actually affected by strong earthquake shaking, it is anticipated that the building may sustain damage. Some stakeholders may deem that this damage exceeds reasonable levels and may attempt to hold the participants in the design process responsible for this perceived poor performance. In this event the engineer of record may be required to demonstrate that he or she has conformed to an appropriate standard of care. It may be more difficult to do this for buildings designed by alternative means than for buildings designed in strict conformance to the building code.

These guidelines recommend the use of independent third-party design review as an inherent part of the design process. Such review, often termed peer review, can help to provide the building official with assurance that a design is acceptable, can suggest approaches that will assist the design team to improve a design's reliability, and can help establish conformance with an appropriate standard of care. It is essential that reviewers possess sufficient knowledge, skill and experience to serve in this role.

#### **1.4 Design Team Qualifications**

Appropriate implementation of the design guidelines presented herein requires sophisticated structural and earthquake engineering expertise including knowledge of:

- seismic hazard analysis and selection and scaling of ground motions

- nonlinear dynamic behavior of structures and foundation systems and construction of mathematical models capable of reliable prediction of such behavior using appropriate software tools
- capacity design principles
- detailing of elements to resist cyclic inelastic demands, and assessment of element strength and deformation capacities under cyclic inelastic loading

Engineers who do not have this expertise and knowledge should not undertake projects utilizing these guidelines, either as the engineer of record or as a third party reviewer.

## **1.5 Basis**

The recommendations presented herein were developed by earthquake, structural, and geotechnical engineering researchers and professionals engaged by the Pacific Earthquake Engineering Research (PEER) Center, under its Tall Buildings Initiative. PEER is a multi-disciplinary research and education center with headquarters at the University of California, Berkeley. Since 1997, PEER has been engaged in engineering research to support the development of performance-based earthquake engineering under funding from the National Science Foundation, the State of California, individual cities, and private industry. At PEER, investigators from over twenty universities and several consulting companies conduct research into earthquake-related geohazard assessment, geotechnical and structural engineering, risk management, and public policy.

The Tall Buildings Initiative has included research into the appropriate performance characteristics of tall buildings in the urban habitat, the characteristics of ground motion that affect tall building performance, appropriate methods of modeling and analyzing tall buildings, as well as research into earthquake-resistant means of construction. The Tall Buildings Initiative also draws from experience gained in the application of performance-based earthquake engineering principles to the seismic design of tall buildings.

These guidelines were developed with funding provided under a grant from the Charles Pankow Foundation.

## **1.6 Limitations**

The guidelines presented herein are intended to provide a reliable basis for the seismic design of tall buildings based on the present state of knowledge, laboratory and analytical research and the engineering judgment of persons with substantial knowledge in the design and seismic behavior of tall buildings. When properly implemented, these guidelines should permit the design of tall buildings that are capable of seismic performance equivalent or superior to that attainable by design in accordance with the present building code provisions. Earthquake engineering is a rapidly developing field and it is likely that knowledge gained in the future will suggest that some recommendations presented herein should be modified. Individual engineers and building officials implementing these recommendations must exercise their own independent judgment as to the suitability of these guidelines for that purpose. The Pacific Earthquake Engineering Research Center, the University of California, the



- 1 Charles Pankow Foundation, the individual contributors to this document and their
- 2 employers offer no warranty, either expressed or implied as to the suitability of these
- 3 guidelines for application to individual building projects.
- 4
- 5

## 2 Design Performance Objectives

### 2.1 Minimum Performance Objectives

Buildings designed in accordance with these guidelines are intended to have seismic performance capability equivalent to that intended for similar buildings designed in full conformance with the requirements of the 2006 *International Building Code*. As presented in commentary to the FEMA 450 *NEHRP Recommended Provisions for Seismic Regulation for Buildings and Other Structures*, the building code is intended to provide buildings conforming to Occupancy Category II of ASCE 7.05 the following performance capability:

1. Withstand Maximum Considered Earthquake shaking, as defined in ASCE 7.05, with low probability of either total or partial collapse
2. Withstand Design Earthquake shaking, having an intensity 2/3 that of Maximum Considered Earthquake shaking without generation of significant hazards to individual lives through design measures intended to assure that nonstructural components and systems remain anchored and secured to the structure and that building drifts are maintained at levels that will not create undue hazards.
3. Withstand relatively frequent, more moderate intensity earthquake shaking with limited damage

The guidelines presented herein seek to provide assurance that these objectives will be satisfied through requirements to:

1. Proportion and configure structures using capacity design principles in which portions of the structure likely to experience inelastic straining are identified and detailed to be able to withstand the anticipated demands with acceptable levels of damage, while other portions of the structure are proportioned with sufficient strength to avoid significant inelastic response.
2. Demonstrate that the structure will be capable of essentially elastic response under Service-level Earthquake shaking having a mean return period of 25 years. Damage in response to service-level shaking can include moderate cracking of concrete and yielding of steel in a limited number of structural elements. Damage occurring in response to Service-Level shaking should not compromise the structure's ability to survive Maximum Considered Earthquake shaking, nor should it result in unsafe conditions requiring repair prior to occupancy. Some repair may be needed to restore appearance or protection from water intrusion, fire resistance, or corrosion.
3. Demonstrate that the structure will respond to Maximum Considered Earthquake shaking: without loss of gravity-load-carrying capacity; without inelastic straining of important lateral-force resisting elements that will severely degrade their strength or render their further response unpredictable; and without experiencing excessive permanent lateral drift or development of global structural instability.

4. Detail all elements of the structure for compatibility with the anticipated deformations of the seismic-force-resisting system under Maximum Considered Earthquake shaking.
5. Anchor and brace all nonstructural components and systems in accordance with the requirements of the building code, or alternatively, such that elements essential to protect life safety would be anticipated to function and other elements would be anticipated to remain in place and not create falling hazards under Design Earthquake shaking.

## 2.2 Enhanced Objectives

It may be desirable to design some structures to achieve performance superior to that described in the previous section. Nothing contained within these guidelines should be interpreted as preventing such design; however, the project design criteria for such projects should explicitly state both the desired performance and the means to be employed by the design team to achieve this performance capability if different from that indicated in Section 2.1. Some means which may be considered to obtain superior performance include:

1. Selection of an alternative, lower probability of exceedance, either for Service Level Shaking or Maximum Considered Earthquake shaking, or both. For example, for structures conforming to Occupancy Categories III or IV, the shaking intensity could be increased by the Occupancy Importance Factors specified for these Occupancy Categories in *ASCE 7.05*.
2. Selection of more restrictive acceptance criteria, potentially including lower limiting levels of lateral drift and/or reduced levels of acceptable cyclic straining of elements
3. Design of the attachment of nonstructural components and systems to withstand shaking more intense than that required by the building code
4. Design to limit residual displacements as a means of ensuring the structure can be repaired following earthquake ground shaking.
5. Incorporating the use of damage-tolerant structural elements that are capable of withstanding cyclic inelastic deformation without degradation or permanent distortion.
6. Incorporating the use of response modification devices including isolation systems, energy dissipation systems, and passive and active control systems.

### 3 Design Process Overview

#### 3.1 Introduction

This section presents an overview of the recommended design process and indicates the sections of this document that provide recommendations for the individual steps of the design process.

#### 3.2 Determine Design Approach

Prior to conducting design in accordance with these guidelines the structural engineer should ascertain that the building official will be amenable to the use of these procedures, that the development team is aware of and accepts the risks associated with design the use of alternative means, that the engineer has the appropriate knowledge and resources, and that construction quality will be adequate to assure the design is properly executed. Section 1.3 provides additional discussion of these issues.

#### 3.3 Establish Performance Objectives

Section 2.1 describes the target performance capability for buildings designed in accordance with these procedures. The structural engineer should discuss these performance criteria with the development team and the authority having jurisdiction and confirm that these will form an acceptable basis for design. If alternative performance objectives are desired these guidelines must be modified to permit attainment of such objectives. Section 2.2 provides discussion of some ways this can be accomplished.

#### 3.4 Seismic Input

These procedures require determination of two levels of design ground motion: a Service-Level motion and Maximum Considered Earthquake shaking motion. Service-Level motion is represented by a 2.5%-damped, elastic acceleration response spectrum having a 25-year mean recurrence interval. Maximum considered earthquake shaking is represented by a 5%-damped elastic acceleration response spectrum conforming to the requirements of ASCE-7.05 and a suite of earthquake ground acceleration records that have been appropriately selected and scaled to be compatible with this spectrum. Section 5 provides guidance on the representation of ground motion and selection and scaling of records.

#### 3.5 Conceptual Design

In this step the engineer must select the structural systems and materials, their approximate proportions, and the intended primary mechanisms of inelastic behavior. In general, principles of capacity design will be used to establish the target inelastic mechanisms. Section 6 presents information that may be useful in developing a conceptual design.

### **3.6 Design Criteria**

The structural engineer of record should develop a formal design criteria document that describes the structural systems and materials of construction, the anticipated mechanisms of inelastic response and behavior, the design performance objectives, and the specific design and analysis measures to be conducted to demonstrate acceptable performance capability. This design criteria document should be submitted to and approved by the authority having jurisdiction and any third party reviewers prior to undertaking substantial design effort. Section 4 presents a suggested outline for project-specific design criteria.

### **3.7 Preliminary Design**

These guidelines recommend the use of dynamic structural analysis to confirm that building designs are capable of meeting the intended performance objectives. In order to perform a meaningful analysis the engineer must develop the building design to a sufficient level of detail to allow determination of the distribution of its stiffness, strength and mass as well as the hysteretic properties of elements that will undergo inelastic straining in response to strong ground shaking. Section 6 presents information that may be helpful to engineers in developing preliminary designs.

### **3.8 Service Level Evaluation**

The Service-Level evaluation is intended to demonstrate that the building will be capable of withstanding relatively frequent, moderate-intensity shaking with limited damage. Section 2.1 describes the performance expectation in this regard. Section 7 presents detailed guidelines for performing the Service-Level evaluation and confirming acceptable performance capability for this level shaking.

### **3.9 Maximum Considered Response Evaluation**

Nonlinear dynamic analysis is used to demonstrate that the building has acceptable response characteristics when subjected to Maximum Considered Earthquake shaking. Section 8 presents guidelines for this evaluation and acceptance criteria for use in confirming acceptable performance capability.

### **3.10 Final Design**

The final design of a tall building will be documented by the construction documents, including detailed drawings and specifications, supported by extensive calculations and analyses that result in the generation of large amounts of data. Section 9 presents guidelines for organizing and summarizing this data in a manner that facilitates review by building departments and third party reviewers.

### **3.11 Peer Review**

The procedures recommended herein entail complex, state-of-practice techniques and the application of expert engineering judgment. Accordingly, independent, third-party

- 1 expert review is recommended. This review should include the design criteria, seismic
- 2 hazards analysis, selection and scaling of ground motions, proportioning, layout and
- 3 detailing of the structure, modeling, analysis and interpretation of results. Section 10
- 4 presents guidelines associated with this review.

## 4 Design Criteria Documentation

### 4.1 General

The structural engineer of record should prepare a formal Design Criteria to document the intended structural systems, performance objectives, any deviations from building code criteria, and the specific loading, analysis, design procedures, and acceptance criteria to be employed in the design. The engineer of record should prepare an initial draft of the project Design Criteria as early in the design process as is practical and should update and revise this document as the design is advanced and the details of the building's characteristics and performance are better understood. The Design Criteria should contain a summary of the overall objectives of the design and be updated at key project milestones. At the conclusion of the design effort, the Design Criteria should provide an accurate summary of the final design and procedures used to demonstrate its performance capability.

**Commentary:** *Clearly and concisely communicating the intent of a building's structural design through a well-prepared "Design Criteria" document is beneficial for all involved in its design, review, and implementation. Within the structural engineer's office, staff members will benefit from consistent and clear direction promoting a well-executed design. Building officials faced with review of the design will gain a clear understanding of how the design is intended to meet or exceed the performance expectations inherent in the building code. Peer reviewers, responsible for completing in-depth review of the design, will benefit from a thorough summary of the design objectives, methods of analysis, and acceptance criteria.*

The structural engineer should submit the design criteria to the peer review and building official for acceptance well in advance of the submittal of documents for building permits.

**Commentary:** *It is important to obtain agreement regarding the proposed design approach as early in the process as is practical in order to avoid expending needless effort using an approach that will not receive approval. Once agreement on the design approach is reached, it should be possible to obtain approval simply by demonstrating that the design conforms to the agreed upon criteria. It should be noted, however, that as the details of a design are developed, it may become necessary to revise the previously anticipated design approach, analytic procedures and/or proposed acceptance criteria. Multiple submissions of the design criteria, as it evolves, may be necessary and should be anticipated by all project participants.*

### 4.2 Criteria Content

The sections below indicate the suggested content for typical project design criteria and the types of information that should generally be included.

## I. Building Description and Location

**Commentary:** The purpose of this section is to provide a basic understanding of the scope of the design project and a framework that will place the specific design criteria presented in other sections into perspective.

### a. General

Provide a brief description of the overall building, including any special or unique features and occupancies. This description should include a characterization of the site, its geographic coordinates and the underlying site conditions.

### b. Description of Seismic and Wind Force-resisting Systems

Provide a brief description of the seismic and wind force-resisting systems. This discussion should include a description of the primary load paths, the anticipated areas of inelastic behavior and any response modification (isolation bearings, passive or active damping) devices that will be incorporated into the design.

### c. Representative Drawings

Provide sufficient floor plans, building sections, and elevations to provide an overview of the building. Drawings should clearly identify the configuration of the primary lateral force-resisting systems.

**Commentary:** Drawings or sketches should contain sufficient detail to illustrate the structural systems.

## II. Codes and References

### a. Controlling Codes, Standards and Other References

Provide a listing of the controlling Building Code, including local amendments; and any Standards, Guidelines, or Reference documents, upon which the design will be based.

### b. Exceptions to Building Code Provisions

Provide a listing of any exceptions or deviations that will be taken from the prescriptive code provisions, together with a brief description of the justification for such exceptions.

**Commentary:** Most buildings designed in accordance with these guidelines will generally conform to the design and construction requirements of the applicable building code, with the exception that a limited number of exceptions or alternative criteria will be employed. Since all of the prescriptive requirements of the building code are presumed to be important to the building's performance, the structural engineer should indicate why non-compliance with any of these criteria will be acceptable for this particular design. Reasons provided could include identification that the requirement is not applicable to the particular



building in one or more ways, or that acceptable performance will be assured by other means.

### III Performance Objectives

Provide a listing of the expected performance objectives for the overall building and its structural and nonstructural components. These objectives should address performance under both Service Level and Maximum Considered level earthquake hazards. A listing of some of the possible components includes:

- Overall Building Performance
- Performance of Structural Elements
  - Walls
  - Columns
  - Beams
  - Braces
  - Floor Slabs
  - Diaphragms
  - Foundations
  - Damping Devices
- Performance of Nonstructural Elements
  - Cladding
  - Partition Systems
  - Elevators
  - Exit Stairs

**Commentary:** *Tabular summary of the performance objectives for each of the important building components at both Service-level and Maximum Considered Earthquake shaking is recommended. Include discussion of intended seismic force resisting elements and gravity elements.*

### IV Gravity Loading Criteria

Provide a description of gravity loading criteria including allowances for key structural and nonstructural components, and live loading to be applied in different portions of the building. Specify any live load reductions to be employed as well as any special loads including vehicular or special equipment.

### V Seismic Hazards

Provide a brief summary of the seismic demands being considered during design including both Service-level and Maximum Considered Earthquake shaking events. The site characterization and definition of specific seismic demands will likely be more thoroughly addressed in a separate report prepared by a seismic ground motion specialist. The purpose of this section is to briefly summarize important details regarding the seismic hazard which will influence the structural design. This section should, as a minimum, include:

- Identification of Site Class per the building code

- Identification of likelihood of seismic hazards other than ground shaking including liquefaction, land sliding, lateral spreading, or inundation.
- Indication of return period, annual frequency of exceedance, and the deterministic or characteristic events that define both the Service-level and Maximum Considered Earthquake shaking events.
- Elastic acceleration response spectra for the Service-level and Maximum Considered Earthquake shaking events
- Define the acceleration histories that will be used for nonlinear dynamic analysis including, a discussion of scaling procedures employed and the specific earthquake events, their magnitudes, the recordings used, and their distances to the site. If amplitude scaling is performed, identify the scale factors used. Provide plots that illustrate the extent to which the individual scaled records and their average compare with the target design spectra. If spectral matching is used, identify the procedures used to perform such matching.

Include the detailed Site Specific Seismic Hazard report as an appendix.

**Commentary:** *It is important that the response spectra and corresponding ground motions to be used in analysis are reviewed and approved by the peer review prior to completing the analytical work.*

## VII Wind Demands

Provide a brief summary of the wind demands being considered during the design including:

- Design wind speed and return period (or annual frequency of exceedance) to be used for strength considerations
- Design wind speed and return period (or annual frequency of exceedance) to be used for service level considerations
- Site exposure characteristics
- Method used to determine wind loadings (analytical or test)

If a wind tunnel test is performed, include the detailed wind tunnel report as an appendix.

**Commentary:** *Even in regions of very high seismic risk, it is quite possible for wind demands to exceed seismic demands for service level events. In addition, wind-induced overturning moments may exceed seismic overturning moments when defining the lower bound strength of the structural system. Wind effects should be evaluated early in the design process.*

## VIII Load Combinations

Provide a summary of all design load combinations that will be used and the specific elements to which they will be applied. Refer to Sections 7 and 8 for further guidance on load combinations.

**Commentary:** *It is likely that a series of different load combinations will be used for different elements. For example, adequacy of foundations will typically be evaluated using Allowable Stress load combinations. Load and Resistance*

Factor combinations will typically be used for dead, live, wind, and seismic demands on structural steel and reinforced concrete elements. Different load combinations may be used for elements that are intended to exhibit inelastic behavior as opposed to those elements that are intended to remain elastic. Service-level load combinations may be different than those used for Maximum Considered Earthquake response. Also, the treatment of floor live loading may be different in the various load cases. It is important to identify the specific application for each load combination presented.

## **IX Materials**

Provide a listing of the material properties to be specified on the design drawings, as well as any assumptions regarding material over-strengths or lower-bound strengths to be used in the design evaluations.

**Commentary:** Expected material over-strengths will be used in developing mathematical models of the structure, attempting to characterize the expected performance as closely as possible. These same material over-strengths will also likely be used in implementing capacity design concepts and/or evaluating demand/capacity ratios of elements with benign modes of failure. Lower-bound strengths are likely to be used in demand/capacity assessments of elements with brittle failure modes or modes that can result in catastrophic consequences.

## **X Analysis**

### **a. Procedures**

Provide a summary of each method of analysis (linear static, linear dynamic, nonlinear static, nonlinear response history) that will be used and the anticipated application and purpose of each of these.

### **b. Analysis and Design Software**

Provide a listing of the various analysis and design tools (software) being used, including the specific version of this software.

### **c. Modeling Procedures and Assumptions**

Provide a summary of the modeling procedures and key assumptions to be incorporated in each evaluation including:

- Material properties
- Section property definition
- Joint stiffness assumptions
- Damping assumptions
- Component models and hysteretic behavior
- Boundary conditions

**Commentary:** Many designs will incorporate different models and analysis procedures for the Service-level and Maximum Considered Earthquake shaking evaluations. Some designs may also incorporate an evaluation of elements for

*Design Earthquake shaking, as identified in the building code. The design criteria should separately and completely describe the modeling approach and assumptions used for each analysis employed.*

## **XI Acceptance Criteria**

Provide a summary of all acceptance criteria to be used in demonstrating that the design meets or exceeds the stated performance objectives for both Service-level and Maximum Considered Earthquake shaking. Include details regarding:

- Strength calculations
- Demand/capacity ratios
- Drift limits
- Deformation limits
- Strain limits

For demands obtained from a suite of nonlinear dynamic analyses, indicate the statistical quantity from the suite of analysis results that will be used to perform evaluations against the acceptance criteria. Refer to Section 8 for further guidance on this subject.

Where strain limits will be used as acceptance criteria, describe specifically how predicted strains will be derived from the analysis.

In addition, indicative details shown to meet the stipulated acceptance criteria should be summarized. Examples include:

- Concrete confinement details
- Slab-column connection details
- Slab-wall connection details
- Moment frame connection details
- Brace connection details
- Collector and drag-strut details
- Damping device details

**Commentary:** *Acceptance criteria are the acceptable values of the various response quantities obtained from the analysis. They can include individual limits on element strength demands, element inelastic deformation demands, and global parameters such as drift. When nonlinear dynamic analysis is performed using suites of ground motions, a suite of demands will be obtained for each of these response quantities. It is not unusual for the coefficient of variation for the values of individual response quantities to range as high as 50%. While it may be appropriate to use mean, or average demands for response quantities associated with the prediction of failure modes that have relatively benign consequences, it is usually appropriate to use more conservative estimates of demand for behavioral modes that can result in catastrophic consequences. Chapter 5 provides additional discussion of the variability inherent in response quantities obtained from suites of ground motions while Chapters 7 and 8 recommend acceptance criteria for different types of elements associated with their several behavioral modes.*

**XII Test Data to Support New Components, Models, Software**

If the design includes innovative components, materials, modeling techniques, or software, include supporting materials justifying their appropriateness. Where laboratory research is used as a benchmark for such justification, provide explicit references to publications documenting the research, if it is public domain, or include copies of test reports in an appendix to the report where the information is not publicly available.

**XIII Appendices**

Include the following materials in appendices, as appropriate.

- A. Geotechnical Report
- B. Site Specific Seismic Hazard Report
- C. Wind Tunnel Report
- D. Research Papers relevant to item XII

## 5 SEISMIC INPUT

### 5.1 General

Seismic design of tall buildings using these guidelines requires characterization of ground motion for two levels of shaking: Service-level shaking and Maximum Considered Earthquake shaking. This chapter provides guidelines for an overall approach that involves: 1) conducting probabilistic or deterministic seismic hazard analysis to define acceleration response spectra for each of these shaking levels; 2) modifying the spectra as needed for local site effects, and; 3) selecting and modifying appropriate accelerograms for response history analysis at the Maximum Considered Earthquake level.

This chapter also provides guidelines for appropriate consideration of Soil-Foundation-Structure Interaction effects. Soil-Foundation-Structure Interaction can significantly affect the way a structure responds to ground shaking. Appropriate consideration of soil-structure-foundation interaction can: 1) affect the location at which motions are assumed to be imparted to the structure; 2) justify reduction in the amplitude of input motions as a result of kinematic effects, and; 3) govern the modeling of subterranean levels, including soil springs, foundation elements, and basement walls.

### 5.2 Seismic Hazard Analysis

Use seismic hazard analysis to determine the appropriate amplitude of the ordinates of acceleration response spectra for the Service-level and Maximum Considered Earthquake shaking level. Two types of seismic hazard analysis may be used. Probabilistic Seismic Hazard Analysis should generally be used to determine ordinates of Service-level shaking and Maximum Considered Earthquake shaking. At sites that are located within 10 kilometres of one or more known active faults, capable of producing earthquakes with magnitudes in excess of M6, Deterministic Seismic Hazard Analysis should also be used for the Maximum Considered Earthquake shaking level. Refer to the requirements of ASCE 7.05, Chapter 21 to determine whether the results of probabilistic or deterministic seismic hazard analysis should be used to define the design spectrum at the Maximum Considered Earthquake shaking level.

#### 5.2.1 Probabilistic Seismic Hazard Analysis

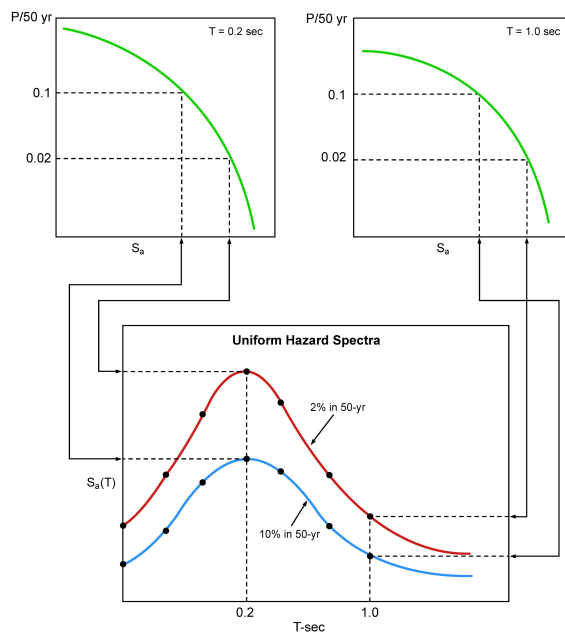
Perform probabilistic seismic hazard analysis for Service-level shaking (25-year return period) and Maximum Considered Earthquake shaking (return period of 2475 years; 2% probability of exceedance in 50 years) using appropriate contemporary models for the description of regional seismic sources and ground motion prediction equations. Ensure that the recent developments in those topics and the use of the models are properly implemented in the probabilistic seismic hazard analysis code being used. The mechanics of probabilistic seismic hazard analysis are described elsewhere (e.g., Stewart et al., 2001; McGuire, 2004) and this section assumes a basic familiarity with the analysis procedures. In probabilistic seismic hazard analysis, account for epistemic (modeling) uncertainties in the input source and ground motion prediction models and in the associated parameter values by including weighted alternatives in the analysis.

Report the following outcomes of probabilistic seismic hazard analysis: 1) mean ground-motion hazard curves at key structural periods including 0.2 seconds, 1.0 second, 2 seconds and the fundamental period of the structure; 2) Uniform hazard response spectra associated with the Service-level (25-year return period) and Maximum Considered Earthquake shaking level, and; 3) percentage contributions to the ground-motion hazard at the key structural periods for each hazard level. These contributions are a function of the seismic source, earthquake magnitude and source-to-site distance, outputs known as the deaggregation of the seismic hazard.

Compute uniform hazard spectra over a range periods extending sufficiently beyond the fundamental mode period of the building to capture the effective period of the building following response to Maximum Considered Earthquake shaking.

*Commentary: The top of Figure 5.1 shows example ground-motion hazard curves at two oscillator periods. Ground motions are read off of the hazard curves for selected probabilities, e.g., a 10% (or 2%) probability of exceedance in 50 years. A uniform hazard spectrum is constructed from such hazard curves. The bottom of Figure 5.1 shows an example of such a spectrum.*

*Like a hazard curve, a UHS has contributions from many sources and consequently, no one earthquake is likely to produce a response spectrum consistent with the Uniform Hazard Spectra at all oscillator periods. This deaggregation information is an important consideration in the selection of acceleration histories, as described further in Section 5.4.*



**Figure 5.1 Derivation of Uniform Hazard Spectra from hazard curves at different periods**

Probabilistic seismic hazard analysis results for any location in the U.S. can be obtained using the USGS seismic hazard tool (<http://earthquake.usgs.gov/research/hazmaps/index.php>). The USGS site is well maintained and is kept current with respect to source models and ground motion predictive equations. When the building code or other seismic regulations call for a “site-specific analysis” of ground motion, a site specific probabilistic seismic hazard analysis is required in lieu of the USGS web site. Site-specific probabilistic seismic hazard analysis can be performed using one of several available commercial codes (e.g., FRISKSP, EZ-FRISK, FRISK88M) and the open source code OpenSHA (Field et al., 2003).

**Commentary:** *Source models describe fault locations, the range of magnitudes that can be produced by a given source and the rate in time with which earthquakes of various magnitudes would be expected to occur. In California, community source models are developed by the Working Group on California Earthquake Probabilities (Field, 2007). At the time of this writing, in California the most recent model is that of Working Group (2007). For areas inside and outside California, the U.S. Geological Survey (USGS) provides details on seismic source models it uses to prepare national ground-motion maps included in the National Earthquake Hazard Reduction Program (NEHRP) Seismic Provisions and ASCE 7 Standards. The latest revisions to the USGS source models can be found in USGS Open File Report 2008-1128 (Petersen et al., 2008). Users may wish to refine the Working Group or USGS characterizations of certain seismic sources based on different interpretations of available data or based on more recent information obtained during site-specific geologic field investigations for a given project.*

*Ground motion predictive equations provide the median and standard deviation of a ground motion Intensity Measure (IM) conditional on parameters related to source (e.g., magnitude, focal mechanism), path (e.g., closest distance, position relative to hanging wall), and site (e.g., average shear wave velocity in upper 30 m of site, basin depth). For shallow crustal earthquakes in tectonically active regions, the best currently available ground motion predictive equations are those developed in the Next Generation Attenuation (NGA) project (Power et al., 2008). Those models should suffice for estimating ground motions from shallow crustal earthquakes in the western U.S. Different ground motion predictive equations are needed for ground motions generated by earthquakes occurring on the interplate (interface between Pacific Ocean and North American tectonic plates) and intraplate (Benioff zone) segments of the subduction zones in the Pacific Northwest or Southern Alaska. Table 5.1 summarizes the recommended empirical ground motion predictive equations for both shallow crustal and subduction sources and their major attributes.*

*Most ground motion predictive equations include a site term that accounts for average site effects. As described further in Section 5.2.3, in many cases this site term is sufficient for practical purposes and no separate modeling of the site response is needed. In other cases, a site-specific analysis of site response is advisable (or required by the Code). Guidelines on analysis of that type are presented in Section 5.2.3.*



As an example of source model variability, there may be several plausible values of the maximum magnitude of an earthquake that could occur on a given fault. Moreover, there are multiple plausible ground motion predictive equations for a given region (e.g., NGA has five sets). The lack of knowledge regarding which model to use within a particular component of probabilistic seismic hazard analysis is referred to as epistemic uncertainty. As shown in Figure 5.2, epistemic uncertainty is ideally incorporated using a logic tree framework with multiple viable values and associated weights of the critical source parameters (e.g., fault slip rate, magnitude recurrence rate, maximum magnitude) and multiple ground motion prediction equations. Further details on probabilistic seismic hazard analysis in a logic tree framework are provided in McGuire (2004).

The main drawbacks to the USGS site are (1) ground-motion hazard is computed for a fixed set of source and ground motion predictive equation inputs, thus eliminating the possibility of revising inputs and recomputing the hazard; (2) hazard is computed for a reference site condition of  $V_{s30}=760$  m/s; hence site effects are not included in the probabilistic seismic hazard analysis and must be added subsequently in a deterministic manner, which can introduce bias (Goulet and Stewart, 2008); (3) the user cannot perform logic-tree analyses to estimate epistemic uncertainties on hazard curves or UHS.

The main drawback to site-specific analysis is that it requires knowledge of probabilistic seismic hazard analysis and the underlying models. Inadequate familiarity typically leads to misuse of the codes and erroneous results. Therefore, users unfamiliar with probabilistic seismic hazard analysis tools and related models should consider using the USGS web site in lieu of site-specific analysis.

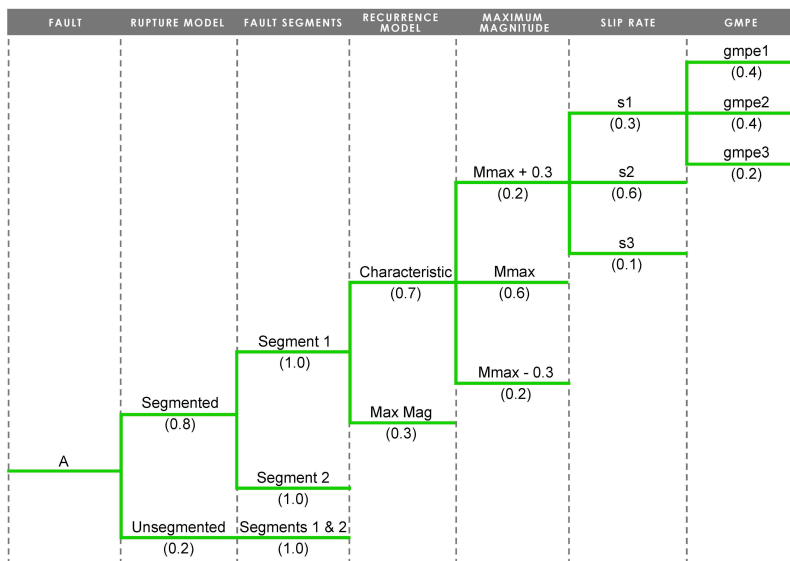


Figure 5.2 Example seismic hazard analysis logic tree

Table 5.1: Selected empirical GMPEs for horizontal response spectra at 5% damping ratio.

Referenc	Regressio Metho <sup>1</sup>	<i>M</i>	<i>R</i> (km)	<i>R</i> <sup>2</sup>	site	<sup>3</sup> sit ter <sup>4</sup>	other <sup>5</sup>	comp <sup>6</sup>	Perio Range <sup>7</sup>
<b>Active</b>									
Boore and Atkinson (2008) -	2-	5-	0-	$R_j$	$V_{s3}$	N	F	gm-	PGA-
Campbell and Bozorgnia (2008)-	2-	4-7.5(n), 8(r), 8.5	0-	R	$V_{s3}$ , 2.	N	$F, \delta_{to}$	gm-	PGA-
Abrahamson & Silva (2008) -	R	5-	0-	$R, R_j$	$V_{s3}$ , 1.	N	$F, W, \delta_{to}, \delta_x, H$	gm-	PGA-
Chiou and Youngs (2008) -	R	4-8(n, r), 8.5	0-	$R, R_j$	$V_{s3}$ , 1.	N	$F, \delta_{to}, \delta_x$	gm-	PGA-
Idriss (2008) -	judgmen	4-8(r), 8.5	0-	R	rock	n	F	gm-	PGA-
<b>Subduction</b>									
Atkinson and Boore (2003, 2008)	1-	5.5-	10-	$r_{Hypo}, R$	rock & soil	N/	h	gm	PGA-
Crouse (1991a,	1-	4-	10-	$r_{Hypo}, R$	soil	n	h	gm	PGA-
Youngs et al.	1-	5-	10-	$r_{Hypo}, R$	rock &	n	$Z_t$	gm	PGA-3 or
Zhang et al. (2006)	R	5-	0-300	$r_{Hypo}, R$	rock & soil	L	h	gm	PGA-

<sup>1</sup> 2-s = two-step regression; RE = random

<sup>2</sup> R = site-source distance;  $r_j$  = surface projection distance;  $r_{hyp}$  = hypocenter distance

<sup>3</sup> R/S = rock/soil;  $v_{s3}$  = average shear wave velocity in upper 30 m of

<sup>4</sup> NL = site effect is nonlinear; L = site effect is

<sup>5</sup> F = style of faulting factor; HW = hanging wall flag; h = focal depth,  $Z_t$  = subduction zone source factor;  $\delta_{to}$  = depth to top of  $\delta$  = fault

<sup>6</sup> Component of horizontal motion considered. gm=geometric mean; gm-rot=orientation-independent geometric mean; ns=not

<sup>7</sup> PGA-10 means 0 to 10 sec, PGA-3 or 4 means 0 to 3 sec for the rock equations, and 0 to 4 sec for soil eqns.

## 5.2.2 Deterministic Seismic Hazard Analysis

Deterministic seismic hazard analysis has the same components as probabilistic seismic hazard analysis (source model, ground motion predictive equations). The difference is that the range of possible results at each stage of the analysis is not considered in deterministic seismic hazard analysis. A single earthquake is considered with a prescribed magnitude and location. A single percentile-level of ground motion is taken from the ground motion predictive equation (e.g., 50 %-tile or median motion). The selections made at the various stages of deterministic seismic hazard analysis are arbitrary and it is often difficult to know *a priori* whether the choices made lead to a conservative or unconservative estimates of ground motion. Nevertheless, the ASCE 7-05 standard, requires the use of deterministic seismic hazard analysis to provide a deterministic cap on ground motion in regions near major active faults (Leyendecker et al., 2000) to limit ground motion to levels deemed "reasonable" for seismic design.

When deterministic seismic hazard analysis is required per Section 21.2 of ASCE 7-05, use the same ground motion predictive equations and weights used in the probabilistic seismic hazard analysis for the controlling fault. Assign the same values to the independent parameters, such as  $V_{s30}$  and fault type, as assigned in the probabilistic seismic hazard analysis. Select the maximum magnitude for the controlling fault that is the weighted average of alternative maximum magnitudes listed in the logic tree used in the probabilistic seismic hazard analysis.

**Commentary:** *More than one fault may produce the largest ground-motion response spectrum. For example, a large magnitude event (e.g.,  $M_{6.5} - 7.0$ ) on a nearby fault may produce the largest ordinates of a response spectrum at short and intermediate natural periods, but a great earthquake (e.g.,  $M \sim 8$  or larger) on a fault farther away may produce the largest long period ordinates.*

*A special case of deterministic seismic hazard analysis is to use physics-based seismological simulation techniques to generate site ground motions for a prescribed earthquake source function coupled with wave propagation analysis. Chapter 6 of Stewart et al. (2001) describes a number of simulation methods of this type. Advantages of seismological simulation tools are that they are able to produce ground motions for large magnitude events that may be critical for the design of long period buildings (because of their long duration and energy content at long periods), but which have not yet been recorded. Moreover, those simulations can consider complex source effects (such as multiple rupturing fault segments, variable slip distributions, etc.) and path/site effects (e.g., basin geometry). The principal disadvantage of these simulation tools is the limited calibration against data and lack of commercial software and understanding of the underlying seismological principles, which has limited their implementation in engineering practice. It is hoped that these limitations will be overcome in the future to allow more engineers to use simulation methods with a higher degree of confidence than is currently possible.*

## 5.2.3 Site-Response Analysis

Perform site response analyses, where appropriate and where required by code. Use either equivalent linear or fully nonlinear methods. Conduct such analyses for several

input ground motions and for variations in the soil constitutive models and material properties, including the shear moduli, material damping ratios and strength, and their variation with shear strain. For sites with potentially liquefiable soils, use fully nonlinear procedures that account for pore pressure generation and dissipation.

Select records for site response analysis for a site condition that is generally compatible with the geologic conditions at the bottom of the site profile being simulated. If bedrock is reasonably shallow and its depth is known, the profile should extend into rock and input motions should be defined for the rock condition. If the site consists of deep soils that cannot be reasonably simulated in their entirety, then the soil profile should extend to a firm soil horizon. In that case, use input motions for weathered bedrock or firm soil conditions. See Section 5.4 for additional considerations for input motion selection.

**Commentary:** When performed for a single dimensional medium, site response analysis is often referred to as “ground response analysis,” which can serve in some cases as a good approximation of the full 3-dimensional site response problem. Ground response analyses are performed for two principal reasons. The first is to improve predictions of free-field ground surface motions relative to what can be obtained using the site term in a ground motion predictive equation. The second is to estimate the variations with depth of motions through the profile, which can be used to define the seismic demand at the ends of soil springs in soil-structure interaction analyses (further details in Section 5.3).

With regard to the first application, site factors incorporated into ground motion predictive equations will often suffice for the analysis of free-field ground surface motions (Baturay and Stewart, 2003). However, ground response analysis can tangibly improve the accuracy of ground motion estimates for sites with a significant impedance contrast (e.g., between a firm bedrock material and soil) and sites with materials that might be expected to experience soil failure at large strains (e.g. highly sensitive clays or liquefiable soils) or produce unusually high motion amplification (e.g. very thick soft to medium stiff clays). The ASCE 7-05 standard requires site-specific site response studies for these and other types of soils designated as Site Class F.

Liquefaction problems are especially challenging in a site response context. Equivalent linear methods cannot capture the full behavior of liquefied soils because they are total stress representations of soil properties. It is generally preferred, therefore, to use fully nonlinear site response analysis for liquefiable sites.

Good descriptions of equivalent linear methods are presented in Kramer (1996). Stewart and Kwok (2008) provide descriptions of several nonlinear codes and commentary on their application.

The commentary to the 2003 NEHRP Seismic Provisions (Part 2) provides guidance on obtaining dynamic soil properties. On-site measurement of  $V_s$  should be used in lieu of correlations between  $V_s$  and other parameters such as penetration resistance. For most practical situations, the use of modulus reduction and damping curves from correlation relationships should suffice, unless large strain response is expected. Recommendations for managing the

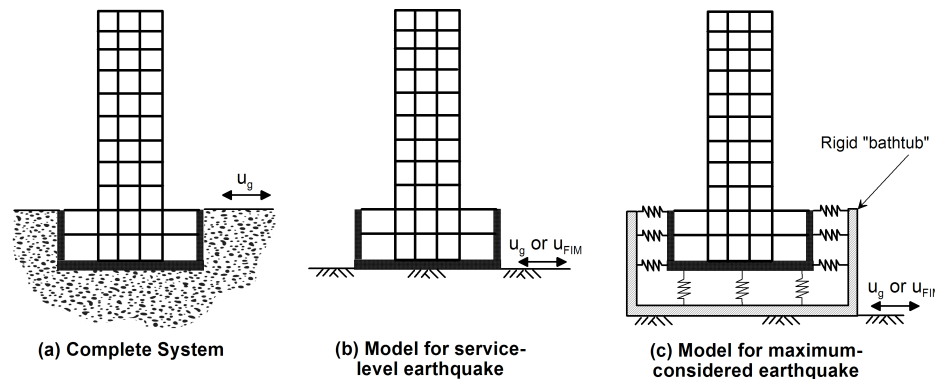
large-strain problem in soil property selection are given in Stewart and Kwok (2008).

Equivalent linear methods cannot simulate pore pressure generation and its effects on soil properties (e.g., Youd and Carter, 2005). However, approximate equivalent linear moduli and damping values can be assigned to liquefied layers based on an analysis of ground motions at vertical array sites that liquefied (Zeghal and Elgamal, 1994; Elgamal et al., 1996). Not all nonlinear codes include pore pressure generation models, so care should be taken in code selection. In many nonlinear codes, pore pressure generation is reflected only by a reduction of the nonlinear backbone curve. This process is a very crude approximation of the soil behavior under dynamic loading because it neglects large-strain dilation. In practice, engineers often attempt to bound the problem by performing two sets of ground-response analysis: one for the soils with no pore pressure generation (total stress analysis) and a second with the pore pressure component of the model activated. The effectiveness of this procedure is poorly understood.

### 5.3 Soil-Foundation-Structure Interaction

Consider soil-foundation-structure interaction effects in accordance with this section when developing analytical models for seismic evaluation of tall buildings with subterranean levels.

**Commentary:** Tall buildings generally have subterranean levels to provide space for parking and other facilities. The most common foundation type is mats, although pile systems are used as well, particularly for tall buildings without subterranean levels. A schematic illustration of a building with subterranean levels is shown in Figure 5.3a. Spatial variations of ground motion cause motions on foundation slabs ( $u_{FIM}$ ) to differ from free-field motions (denoted  $u_g$  in Figure 5.3a), which is referred to as a kinematic interaction effect.



**Figure 5.3 Schematic illustration of tall building with subterranean levels and simple models for analysis in which soil-foundation interaction effects are neglected (Part b) and included in an approximate manner (Part c). Part (c) only shows springs but parallel dashpots are generally also used.**

5.3.1 Service-level analysis

Extend analytical models used for Service-level response analysis to the structure's base, as shown in Figure 5.3b. Include the subterranean levels in the structural model used for dynamic response analysis. Include appropriate element stiffness and capacities for structural members such as walls, columns, and slabs. Soil springs need not be included in the model. Motion should be applied at the base of the structure and can consist either of free-field motion ( $u_g$ ) or the foundation input motion ( $u_{FIM}$ ), which is modified for kinematic interaction effects.

5.3.2 Maximum Considered Earthquake shaking analysis

Include subterranean levels, springs and dashpots representing foundation-soil interaction along basement walls and below the base slab, as shown in Figure 5.3c. Input ground motions to the model via a rigid "bathtub" surrounding the subterranean portions of the structure. Input motion can consist either of free-field motion ( $u_g$ ) or the foundation input motion ( $u_{FIM}$ ), which is modified for kinematic interaction effects

**Commentary:** An approach similar to that described above for buildings with mat foundations should be implemented for pile foundations. Typical engineering practice for this foundation type is to (1) define the free field ground motion at the level of the pile caps, (2) excite the building with this motion or feed the motion through linear springs/dashpots attached to the pile cap to model the soil-pile interaction, (3) compute the base forces and moments, and (4) input them in a separate soil-pile interaction model to obtain the pile responses.

Procedures for analysis of kinematic interaction effects are given in FEMA-440, ASCE-41 and Stewart and Tileylioglu (2007). Those effects are generally most pronounced at short periods (less than approximately 1 sec), and hence are unlikely to significantly affect fundamental mode responses of tall buildings.

The stiffness and damping characteristics of the foundation-soil interaction should be characterized by distributed springs and dashpots acting around the foundation (illustrated in Figure 5.3c). The distributed springs and dashpots can be calculated from impedance functions for rigid foundations (e.g., Gazetas, 1991). Further details and examples are given in ATC 40, FEMA 356, ASCE 41, and Naeim et al. (2008).

The above approach for pile foundations is reasonable for relatively stiff and stable soils, but it may not be acceptable for soils susceptible to failure, where the soil-pile interaction becomes highly nonlinear. In those situations, an iterative solution technique can be implemented in which trial values of equivalent linear springs/dashpots are selected until the base-level displacements computed from the dynamic analysis of the building are compatible with the pile-cap displacements computed from the application of the building base forces and moments to the soil-pile model. Relatively advanced 3-D nonlinear finite element or finite difference modeling can also be performed in which the building, its foundation, and the soil are considered in a single model. However, such models are generally not practical at the present time. General guidelines for analysis of

foundation springs for deep foundations are given in Salgado (2006) and the 2003 NEHRP commentary (Chapter 5.6).

## **5.4 Selection and Modification of Accelerograms**

### **5.4.1 Introduction**

Select and modify accelerograms for structural dynamic analyses at the Maximum Considered Earthquake level using the following steps:

1. Identify the types of earthquakes that control the ground motion hazard.
2. Select a representative set of at least seven pairs of accelerograms recorded during past earthquakes that are compatible with the controlling event and site condition.
3. Modify those motions in some manner to achieve a match with the target spectrum, either using spectral matching or amplitude scaling.

The following sections provide details on these processes

### **5.4.2 Identification of Controlling Sources**

Where Maximum Considered Earthquake shaking is controlled by probabilistic seismic hazard analysis, deaggregate the ground-motion hazard for the 2% in 50-yr spectral accelerations at the structural natural periods of interest, and use the results as the basis for selecting representative accelerograms for response history analysis. The structural natural periods of interest will include, as a minimum, the fundamental periods of structural response in each of the structure's two principal orthogonal directions of response.

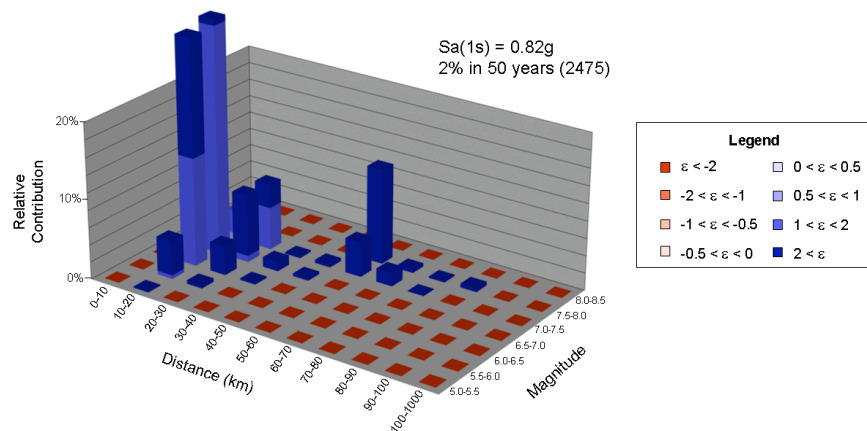
**Commentary:** Depending on the structure's dynamic characteristics, and the source distance and magnitude for significant events identified in the deaggregation, it may be appropriate to consider additional periods including the periods corresponding to higher modes of structural response and periods corresponding to lengthening of the fundamental periods as the structure experiences damage.

Probabilistic seismic hazard analysis involves the calculation of ground motion hazard considering a large number of possible future earthquakes having different magnitudes and locations relative to the site. Some of the considered earthquakes contribute much more to the computed hazard than others. Deaggregation of a point on the hazard curve identifies the relative contributions of various seismic sources, earthquake magnitudes and distances to the computed ground motion. The deaggregation is specific to a ground motion intensity measure (e.g., spectral acceleration at a particular period), hazard level (e.g., 2% probability of exceedance in 50 years) and site condition. An example deaggregation for a site in Los Angeles is shown in Figure 5.4.

In the figure, the height of the bars at different magnitudes and distances provides information on controlling sources. Deaggregation can also provide information on the degree to which relatively average or extreme ground motions from the ground motion prediction equations contribute to the hazard. This is accomplished through the parameter  $\varepsilon$  (epsilon), which is defined as:

$$\varepsilon | (M, R) = \frac{\ln(IM) - \mu | (M, R)}{\sigma | (M, R)} \quad (5.1)$$

where  $IM$  is the level of the ground motion intensity under consideration (e.g., a spectral acceleration of 0.5 g at a specific period of interest),  $\mu$  is the median ground motion for a given magnitude and distance ( $M$  and  $R$ ) from a ground motion predictive equation and  $\sigma$  is the standard deviation from the ground motion predictive equation. Values of  $\varepsilon$  for different  $M$ ,  $R$  combinations are shown by the colors of the bars in Figure 5.4. The dark blue colors in the figure indicate that relatively extreme realizations of the ground motion predictive equation are controlling the hazard (i.e., ground motions well beyond the median). An understanding of epsilon as well as  $M$  and  $R$  is used for the selection of accelerograms, as described below.



**Figure 5.4 Example hazard curve for a site in Los Angeles. The selected IM is 5%-damped 1.0 sec pseudo spectral acceleration and the hazard level is 2% probability of exceedance in 50 years. (Goulet et al., 2007).**

For very tall buildings, the fundamental period could be 4 sec or more, which can introduce several practical challenges. First, the deaggregation data from the USGS website is only available for periods of 2 sec or less. Because deaggregation results are generally strongly period-dependent, hazard analysis based on the USGS site should not be used for buildings with fundamental periods significantly beyond 2 sec. The NGA ground motion predictive equations are capable of predicting ground motions up to 10 sec for active regions. For subduction earthquakes, ground motion predictive equations are not available for



periods beyond 3-5 sec, which precludes direct hazard analysis and deaggregation at longer periods. The NEHRP Provisions (Section 11.4 and Chapter 22) provide guidelines for extrapolation of spectra to long periods, but deaggregation remains out of reach for such situations.

#### 5.4.3 Record Selection

As required in current building codes, use a minimum of seven accelerogram sets for response history analysis. Each accelerogram set selected must consist of at least two horizontal components, and in rare cases, the vertical component may also be included. Select records that are generally compatible with the earthquake magnitude and site-source distance found from deaggregation. If multiple magnitude-distance combinations contribute significantly to the hazard, then select records from each contributing earthquake as part of the total number of records.

When representative accelerograms from great earthquakes controlling the seismic hazard are not available or are too limited, then the seismological simulation tools described in Section 5.2.2 should be used to develop additional ground-motion records in such cases.

When the hazard is controlled by faults producing moderate to large magnitude earthquakes at close distances to the site, an appropriate number of the selected ground-motion records should include near fault and directivity effects, such as velocity pulses producing relatively large spectral ordinates at relatively long periods.

**Commentary:** Two important considerations in record selection are the number of records to be used for analysis and the attributes of the selected records. If the intent of response history analysis is to reliably characterize both the central value (mean or median) of demand parameters as well as the possible dispersion, a large number of record sets, on the order of 20-30 would be needed because of significant scatter of structural response to ground motion. However, it has become standard practice to use fewer records because of practical difficulties in running large numbers of nonlinear response history analyses. When these smaller numbers of records are used for analysis, the dispersions in response quantities obtained from the analysis should not be considered to be a reliable estimate of the true dispersion. Such dispersions should be either adapted from other research projects that used much larger sets of input ground motions (e.g., Goulet et al. 2007, Moehle et al, 2008), or the designer should use a much larger set of input motions to estimate the scatter of the structural responses. Analyses using suites of at least 20 to 30 appropriately selected and scaled records are probably necessary to obtain meaningful estimates of standard deviation.

It will not generally be necessary to include vertical motions in the analysis. Such motions should be included when the structure includes very long spans, large cantilevers and similar elements that could be sensitive to response to vertical shaking.

The attributes of records that should be selected to be compatible with the controlling earthquakes for a site have been the subject of a great deal of recent

research and a broad consensus has yet to materialize in engineering practice. The recommendation to use records from events with comparable earthquake magnitude and site-source distance found from deaggregation is compatible with current practice, however.

Where multiple earthquake events have significant contribution in the deaggregation, it may be necessary to select a larger suite of motions than the seven typically used, to adequately capture the range of response the structure may exhibit in events that could produce Maximum Considered Earthquake shaking.

As described in Section 5.4.2, deaggregation of seismic hazard for long-period spectral accelerations will often indicate large magnitude earthquakes as a controlling source. Record selection for such events is challenging because few such events have been recorded.

The local station geology and fault type of the causative earthquake are also frequently considered in the record selection; however, the number of records that have magnitudes, distances, fault type and local geology similar to that of the controlling earthquake may restrict candidate accelerograms to an unacceptably small number.

Recent research has suggested that the aforementioned record attributes of magnitude, distance, etc. can produce large dispersion in predictions of certain response quantities such as interstory drift (e.g., Baker and Cornell, 2006a). This has motivated the development of an alternative approach for record selection, in which the focus is on spectral shape near the periods of interest in lieu of (or in combination with) magnitude, distance, and similar parameters. Parameter epsilon (defined in Eq. 5.1) has been found to be correlated to spectral shape (Baker and Cornell, 2006a), with large epsilon at a given period ( $T_1$ ) typically associated with rapid decay of spectral ordinates for  $T > T_1$ . To use epsilon as an attribute for record selection, epsilon values would need to be computed for individual recordings using appropriate ground motion predictive equations, and those values would need to be compiled in a searchable database. That work has not been completed to date, which limits the use of epsilon in practice for record selection. The target values of epsilon for record selection are those identified from deaggregation (e.g., Figure 5.4).

When using seismological simulation techniques, engineers are cautioned to only use motions from adequately calibrated models that are judged to provide reasonable results. The selected simulation method should incorporate realistic models of fault rupture and wave propagation, including the effects of alluvial basins, which are known to amplify long period ground motions. Moreover, the simulations should be repeated for multiple reasonable realizations of key source parameters (such as slip distribution, rupture velocity, rise time, etc.).

#### 5.4.4 Modification of Accelerograms to Match Target Spectra

Match records either to the uniform hazard spectrum or conditional mean spectrum. If the conditional mean spectrum approach is used, use a suite of conditional mean spectra, each matched to one of the key periods described in Section 5.4.2.

Match records to the target spectra either by direct scaling or spectral matching.

**Commentary:** *There are two principal considerations in the modification of accelerograms to match target ground motion intensity measures. The first is the manner by which the record is modified. The second consideration is the target intensity measure that should be considered in the modification process. The intensity measures used in typical engineering applications are elastic response spectral ordinates; hence the target takes the form of one or more response spectra.*

*Two principal procedures are used for ground motion modification: direct scaling and spectral matching. The direct scaling procedure consists of determining a constant scale factor by which the amplitude of an accelerogram is increased or decreased. Because elastic response spectra correspond to linear response of a single-degree-of-freedom system, the same scale factor applies to spectral accelerations at all periods. Spectral matching adjusts the frequency content of accelerograms until the response spectrum is within user-specified limits of a target response spectrum over a defined period band. Modifying the frequency contents of ground-motion records can be performed in either the time or frequency domain. Generally, the time domain modification of a record, by adding appropriate wavelets to the original time series, has been the preferred procedure, although both methods work equally well when the response spectra of the selected records are similar in shape to the target spectrum. Alternative procedures for spectral matching are elaborated in Chapter 7 of Stewart et al. (2001).*

*Target spectra can be developed using one of the two following options: (1) the design response spectrum developed from building code procedures (which corresponds roughly to the uniform hazard spectrum for the site) or the uniform hazard spectrum from site-specific analysis; or (2) site-specific scenario spectra (one or more) that preserve realistic spectral shapes for controlling earthquakes and which match the design spectral ordinate at periods of interest to the nonlinear response. In the case of Option 1, the target spectrum is a direct result of the ground motion hazard analysis. For Option 2, the target spectrum represents a modification of the uniform hazard spectrum, and the conditional mean spectrum approach of Baker and Cornell (2005) is an effective approach for defining the scenario spectrum.*

*For sites within a few kilometers of an active fault that governs the ground-motion hazard, target response spectra should be developed for the fault-normal (FN) and fault-parallel (FP) directions. Those differences arise due to rupture directivity effects, which are most pronounced at long periods. Through a coordinate transformation, the two horizontal components of each selected accelerogram would be adjusted to the FN and FP directions of the fault generating the motions. If the building's principal axes closely align with the FP and FN directions, then the question of how to design for long period motions that are generally much greater in the FN direction will need to be addressed.*

*The conditional mean spectrum matches the uniform hazard spectrum at a selected period but falls below the uniform hazard spectrum at other periods. The shape of the conditional mean spectrum is more physically realistic than that of the uniform hazard spectrum, which is the principal benefit of its use. When scenario spectra are utilized, the records are typically selected in consideration of  $\varepsilon$ , because the emphasis of both  $\varepsilon$  as a record attribute and conditional mean spectrum as a target spectrum is the spectral shape. Baker and Cornell (2005) describe the mathematical procedure for computing conditional mean spectrum for a given matching period. The matching periods should be selected in consultation with the structural engineer, and will include the elongated fundamental mode period of the structure due to inelastic structural response. Higher mode periods should also be considered, especially for such response parameters as shear force in concrete walls that are significantly influenced by higher modes. Note that considering additional periods implies additional conditional mean spectrum, and hence additional response history analyses. When multiple conditional mean spectra are used, multiple suites of each response parameter are obtained from response history analyses. In this case, the envelope value of the response parameter from each suite of analyses should typically be used for design purposes. For example, if three conditional mean spectra are used, one indexed to the buildings first mode period, one to the second mode period, etc., the mean values of response parameters from each of the suites of motions scaled to these spectra should be obtained, and then the maximum of these values should be used.*

*The following comments are provided on the four methods noted above:*

- Present building codes do not currently contain provisions for scenario-based target spectra like the Conditional Mean Spectrum. Hence such spectra can only be utilized for projects for which the building official has approved an exception to code requirements. Code-required design spectra are loosely related to uniform hazard spectra.*
- Direct scaling is usually performed in such a way that the average response spectrum of the ensemble of scaled accelerograms is within specified limits of the target response spectrum over a code-specified period band (e.g., ASCE 7-05). The variability of the records over that period range will contribute to response variability, which can be useful in the design process.*
- Spectral matching is better suited for obtaining relatively stable estimates of mean building response but will always underestimate record to record response variability.*
- Ensembles of recordings will generally have average spectral shapes more compatible with conditional mean spectra than uniform hazards spectra; hence the use of conditional mean spectra should streamline the ground motion selection and modification process. Likewise spectral matching to a uniform hazard spectrum may lead to more unrealistic waveforms than scaling to a conditional mean spectrum.*

## 6 PRELIMINARY DESIGN

### 6.1 General

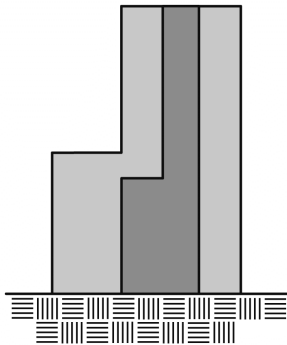
The growing body of experience resulting from the design of tall buildings using performance-based procedures provides much insight that can be used to guide the preliminary design process. This section provides a resource, highlighting important topics shown by experience as critical to consider early in the design process.

**Commentary:** *Providing a step-by-step guide for the preliminary design of tall buildings conflicts directly with the design innovations these towers many times evoke. Each building and site offers new and unique challenges, requiring careful and specific consideration without preset formulation. The creative design process is generally nonlinear, therefore a formal recipe seems out of place. In keeping with this ideal, this section pursues an alternative route of suggesting important design considerations but not providing prescriptive approaches to resolution of the associated design issues.*

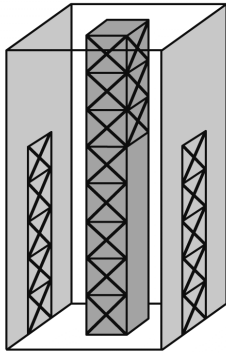
### 6.2 System Configuration

To the extent possible, configure the structure to include a simple arrangement of structural elements with clearly defined load paths and regular structural systems. Configurations and geometries which complicate behavior, add to uncertainty, and which should therefore be avoided to the extent possible include:

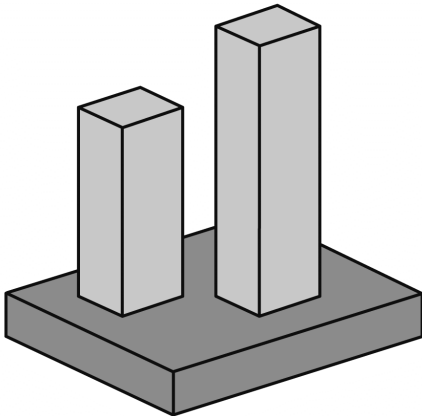
- Large changes in building stiffness (Figure 6.1)
- Large changes in building mass (Figure 6.1)
- Repositioning of bracing elements from floor to floor (Figure 6.2)
- Interaction of two or more towers through a common base structure (Figure 6.3)
- Significant column transfers or offsets (Figure 6.4)
- Gravity induced horizontal shear forces caused by system eccentricities (Figure 6.5)
- Limited connectivity of bracing elements to floor diaphragms



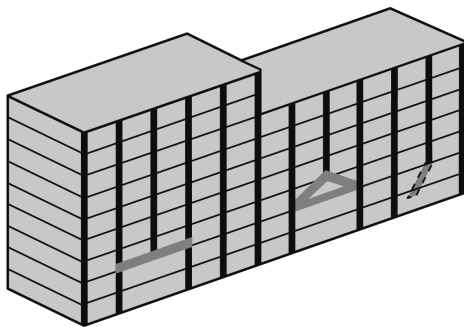
**Figure 6.1 Illustration of building with large changes in stiffness and mass**



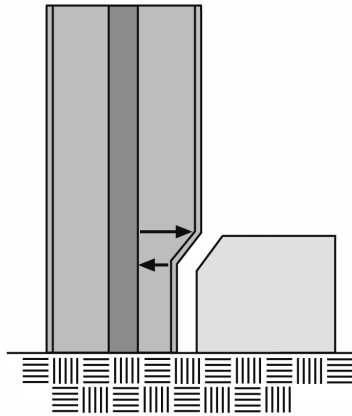
**Figure 6.2 Illustration of lateral system with bracing elements repositioned over structure's height**



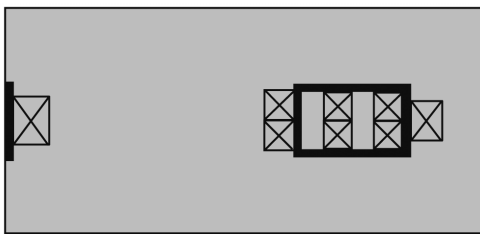
**Figure 6.3 Illustration of two towers on a common base**



**Figure 6.4 Illustration of undesirable column transfer and offset conditions**



**Figure 6.5 illustration of building geometry resulting in gravity-induced shear forces**



**Figure 6.5 Illustration of diaphragms with limited connectivity to vertical elements of the seismic force resisting system**

**Commentary:** Avoidance of the condition discussed above will allow for a greater degree of confidence in predicting system behavior. The assumptions inherent in any mathematical model of a structure add to the uncertainty in predicting behavior. Some of these uncertainties can be eliminated through a simple, well-conceived geometry, thus reducing the analytic studies required to test and prove system behavior.

A regular, well-defined system may seem to run against the grain of modern architectural expression. However, a disciplined approach to the architectural design of a tall building, incorporating important structural principles, will generally lead to the most well-behaved and economical structure.

This list of irregularities described is by no means comprehensive, nor can these items be avoided in all buildings. As a structure becomes more complex, the uncertainty in predicting its response escalates, requiring more robust analytic work to adequately test and demonstrate performance.

### 6.3 Structural Performance Hierarchy

As the structural concept(s) for a tall building is being developed, clearly identify zones or elements where nonlinear response is anticipated. Capacity design concepts are a good starting point when considering desirable system and element actions. While a strict application of capacity design may not be practical or even warranted in the final design, early consideration of these principles will help establish a clear hierarchy to the anticipated building response and will serve to guide the development of the design, which will later be confirmed through nonlinear response history analysis.

**Commentary:** Identification of zones of inelastic response will provide clarity in the overall design approach and the ensuing analytic work. In addition, contemplating the hierarchy of likely response actions to increasing levels of ground motion will provide direction to guide the details of the design to follow.

Capacity design approaches provide a useful means to configure a structure to produce predictable inelastic behavior. However, the higher mode response common in tall buildings can lead to inelastic behavior in zones that simplistic approaches to capacity design will be unable to predict. Ultimately, engineers must rely on analytical verification of behavior to detect any additional zones of inelastic behavior other than those suggested by initial capacity design proportioning of the structure.

### 6.4 Wind

Ensure that the lateral force resisting system is adequate for wind resistance considering both strength and serviceability criteria.

**Commentary:** While this guide focuses primarily on seismic design, it is important to remember that the structural response to wind effects may control the strength and stiffness requirements for a tall building. Many times occupant comfort related to building accelerations in wind events is the controlling design criteria, directly influencing the required building stiffness to appropriately manage these actions.

The overall strength of the structural bracing system may be controlled by wind demands. Wind overturning moments and shears in most tall buildings are more closely related to first mode dynamic response, whereas seismic overturning moments and shears can be heavily influenced by higher dynamic modes of vibration. The net result can be substantially higher wind demands as compared to seismic demands at the base of a tall building, whereas seismic demands may find their peak at the mid-height of the tower.

Wind tunnel studies which capture the dynamic actions of a tall building within the context of its surroundings are important.

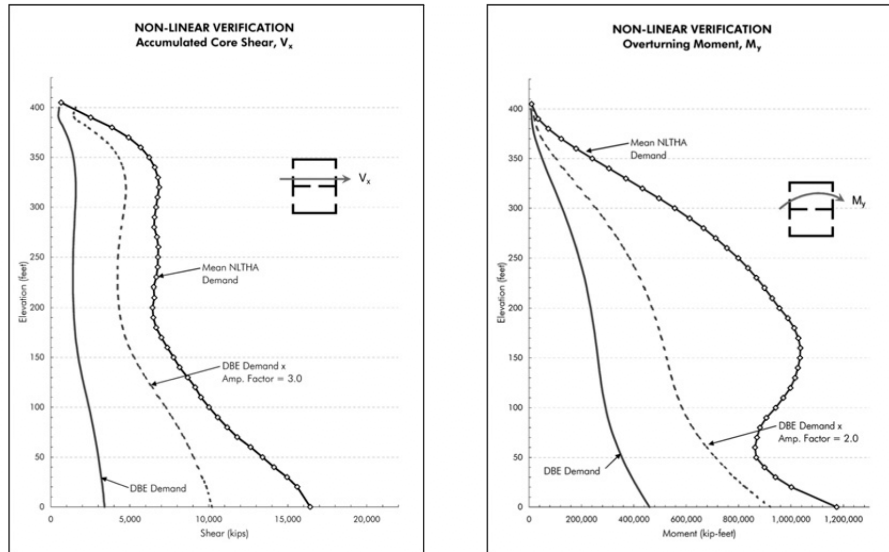
### 6.5 Higher Mode Effects

Consider the potential effects of higher mode response when proportioning the main seismic force resisting system.



**Commentary:** It is common for tall building response to ground shaking to be heavily influenced by higher dynamic modes of vibration. However, traditional engineering practice has focused strictly on the first translational mode when setting strength requirements and lateral force distributions. For tall buildings, the second or even third mode of vibration can be equally, if not more, important to the overall design.

As illustrated in Figure 6.6, the influence of these higher modes of vibration can result in significantly higher flexural demands, well above a building's base, as well as shear demands three to four times greater than those anticipated by a typical prescriptive design. Failing to recognize and incorporate these demands into a tower's design can lead to undesirable performance.



**Figure 6.6 Higher mode effects on shear and flexural demand distributions in a tall core-wall building**

## 6.6 Seismic Shear Demands

Consider limiting shear demands in concrete walls under Service-level seismic forces to the range of  $2\sqrt{f'_c} - 3\sqrt{f'_c}$ .

**Commentary:** As noted in the previous section, the dynamic behavior of high-rise buildings can lead to very high shear demands near the base of the tower. Experience has shown that limiting Service-level shear stresses in concrete walls to  $2\sqrt{f'_c} - 3\sqrt{f'_c}$  will generally result in ultimate shear demands within maximum shear stress limits, considering Maximum Considered Earthquake ground motions.

## 6.7 Evaluation of Building Deformations

Consider limiting roof displacement predicted by elastic response spectrum analysis under Maximum Considered Earthquake shaking to less than 3% of building height.

**Commentary:** Evaluation of overall building deformations at the preliminary design stage offers insight, although limited, to the anticipated behavior considering maximum demands levels. Maximum building displacements in the range of 2 to 3 percent of overall height are generally viewed as acceptable for protecting against global instability under Maximum Considered Earthquake shaking. The dynamic characteristics of tall buildings are such that median estimates of total inelastic displacement are predicted well by elastic spectral analysis as long as the structure is not displaced to deformations near those associated with large inelastic demands.

Interstory deformation is a more complex action to evaluate. While traditional design practice has focused purely on translational movements, actions in tall buildings related to racking can be equally important. An AISC Journal paper (Griffis, 1993) provides greater insight on this topic. Interstory deformations and their impact on architectural finishes are the key design parameters to consider.

## 6.8 Setbacks and Offsets

Attempt to avoid setbacks and offsets in the lateral force resisting system. Where such geometric configurations are unavoidable due to architectural considerations, consider the provision of supplemental strength and/or detailing for ductile behavior in the areas of these conditions.

**Commentary:** Setbacks in overall building geometry or offsets in lateral bracing elements generally lead to a concentration of demands. Care should be taken in these areas during preliminary design to allow for adequate member sizing, anticipating robust detailing requirements in the final design.

Setbacks in concrete core walls or lateral bracing can result in a high concentration of strain demands through the geometry transition. The potential results include localized yielding of structural elements and the need for robust concrete confinement and/or steel detailing.

Offsets in bracing systems can result in significant diaphragm demands. Due consideration of the stiffness degradation of these transfer diaphragms as well as the details of structural "drag" and/or chord elements is recommended.

## 6.9 Diaphragm Demands

Pay careful attention to the configuration and strength of diaphragms at transitions in the lateral force resisting system.

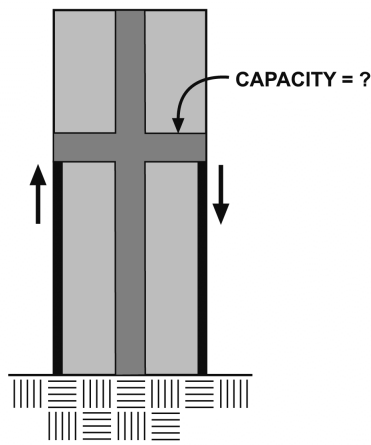
**Commentary:** Diaphragm demands on the floor systems for typical high-rise floors are generally nominal, unless the given floor configuration is long and

*slender with widely spaced bracing elements or features offsets in the primary lateral bracing system.*

*Diaphragm demands at transitions in building geometry (such as a podium structure) or at the base of a building can be extraordinary and warrant special attention early in the design process. Large shear reversals (back-stay forces) may be predicted by the analytic models of the structure. If these load paths are to be realized, many times limitations on diaphragm openings and offsets are required. These requirements can be particularly onerous at the ground level of a building where garage entry ramps, loading docks, retail spaces, and landscaping design often result in geometrically complex floors. Early coordination with the architect is imperative to ensure adequate load paths will exist in the completed structure.*

## 6.10 Outrigger Elements

Outrigger systems are often included in the design of high-rise buildings in order to reduce overturning demands on slender vertical elements of the lateral force resisting system (Figure 6.7). It is important to consider the impact of the outriggers on the supporting columns and walls under maximum demand levels. For example, an outrigger supported by a perimeter column may be capable of delivering an axial load much greater than traditionally considered. Evaluating the over-strength characteristics of an outrigger system and the potential impacts on axial and shear demands is critical to ensuring the overall building system will perform as expected.



**Figure 6.7 Illustration of outriggers used to reduce overturning demands at base of vertical elements of the seismic force-resisting system**

## 6.11 Non-participating Elements

Consider the impacts of all building elements on the ultimate behavior and element demands. In addition to providing for deformation compatibility of gravity load resisting

elements consider that axial and shear demands on columns and walls can be significantly influenced by interaction with "gravity framing."

**Commentary:** *Traditional seismic design practice has assigned primary bracing requirements to a few select elements, while the remaining features of the structure have been deemed as "non-participating elements." This is merely a simplification of the real building actions. Elements intended only to provide gravity resistance can greatly influence the behavior of the main lateral force resisting system and also attract substantial seismic induced stresses themselves.*

## 6.12 Foundations

The subject of soil-structure interaction is complex and not well understood at this time. Due consideration should be given to the uncertainties related to soil-structure interaction. Traditional practice has input seismic ground motions at the ground's surface in the form of free-field motions. Many times, tall buildings have significant substructures which may play an important role in overall building behavior. A well-considered approach to this topic should be developed during the preliminary design stage. Bounding the response of the structure by varying the foundation support assumptions may be a practical way to address this complex issue. For more detailed discussion of this topic, see Section 5.

## 6.13 Slab – Wall Connections

Important to the integrity of buildings supported in whole or part by concrete core walls is the connection between the floor slabs and core walls. As a tower sways due to wind or seismic induced motion, slab-wall connections rotate due to the translation of the structure. In addition, these connections experience vertical motions due to the elongation of the core walls. These vertical displacements compound the translation demands for top reinforcing.

These demands as they relate to post-tensioned floor slabs were investigated and reported in an article entitled "Performance of Post-Tensioned Slab-Core Wall Connections" by Klemencic, Fry, Hurtado, and Moehle, (PTI Journal, December 2006). Specific detailing suggestions are made in this article to enhance the performance of this connection.

## 6.14 Slab – Column Connections

Robust detailing of slab-column connections is also important to the integrity of tall concrete buildings. As slab-column connections experience lateral deformations, increased moment and shear demands result. These demands may result in yielding of slab reinforcing steel. More critical is the increased shear demand. Robust details which address/prevent punching shear failure are essential.

**6.15 Damping**

Assumptions related to the levels of damping provided by structural and non-structural elements at various demand levels are the subject of ongoing debate and discussion. In general terms, damping levels lower than the traditionally assumed 5 percent are likely appropriate for Service-level evaluations. Research results reported by the AIJ have indicated damping ratios between 1 to 3 percent may be more appropriate for Service-level evaluations of wind and seismic events.

As demand levels increase and structural damage occurs, damping levels will surely increase. However, little research exists to guide appropriate analytic assumptions when considering maximum demand levels. Further, the hysteretic damping offered by the nonlinear action of yielding elements is generally captured through a rigorous nonlinear response history analysis. Suffice it to say, care should be taken to limit damping assumptions to modest levels to avoid unrealistic predictions of building behavior. The ATC-72 publication and Chapter 8 offer further insights to this topic.

## 7 SERVICE LEVEL EVALUATION

### 7.1 General

Perform Service-level evaluations of tall buildings in accordance with this section. Topics covered herein include shaking hazard level, performance objectives, modeling requirements, design parameters and acceptance criteria.

### 7.2 Service-level Earthquake Shaking

Service-level earthquake shaking shall have a mean return period of 25 years. Service-level Earthquake shaking shall be represented in the form of a site-specific, uniform hazard, elastic acceleration response spectrum with an appropriate level of damping. In lieu of detailed justification for higher levels of damping, the percentage of critical damping for construction of the site specific design spectra may be taken as 2.5%. For buildings in Occupancy Category III (ASCE 7-05, § 1.5.1) the ordinates of spectral accelerations shall be multiplied by 1.25.

**Commentary:** System response identification of instrumented buildings during past earthquakes where the buildings have suffered no noticeable damage indicate that percentage of critical damping most commonly associated with fundamental period of these buildings varies between about 1% to 2%. Higher values of damping, however, have been identified for higher modes of response (see ATC-72 report and Naeim et al. 2008). Since elastic response of a tall building is invariably a multimode response, a default value of 2.5% damping for all modes provides a simple and conservative estimate of the level of damping associated with multi-mode service level response of tall buildings to service level earthquake ground motions.

The 1.25 spectral acceleration multiplier for buildings in Occupancy Category III is intended to produce buildings with higher strength consistent with the prescriptive requirements contained in ASCE 7-05, § 11.5.1)

### 7.3 Analysis Method

Three-dimensional elastic response spectrum analysis (using two horizontal components of motion represented by the elastic design spectra defined in Section 7.2) shall be performed to assess the seismic performance of the building under Service-level Earthquake shaking. The analysis shall include sufficient modes to include participation of at least 90 percent of the building's mass for each principal horizontal direction of response. Modal responses shall be combined using the Complete Quadratic Combination (CQC) method. The corresponding response parameters, including forces, moments and displacements, termed herein Elastic Response Parameters shall not be reduced. Expected material properties shall be used in the mathematical structural analysis model (see Table 7-1).

## 7.4 Performance Objective

When subjected to Service-level earthquake shaking, some very limited damage may be permissible. This damage if not repaired, should not affect the ability of the structure to survive future Maximum Considered Earthquake ground motions. However, repair may be appropriate or required for cosmetic purposes and to avoid compromising the building's long term integrity for fire resistance, moisture intrusion and corrosion.

**Commentary:** Tall buildings may have useful lives of 100 years or more. Therefore, shaking with a 25 year return period is representative of events that a tall building may be expected to experience several times during its useful life. Because tall buildings are important structures, that may house hundreds to thousands of individuals, either as residences or places of business, it is desirable that the building remain operable during and immediately after such an event. Such performance is achievable with minor structural damage that does not affect either immediate or long term performance of the building and therefore does not compromise safety associated with continued building use. Repair, if required, should generally be of a nature and extent that can be conducted while the building remains occupied and in use, though some local disruption of occupancy, around the areas of repair may be necessary during repair activities.

It is important to note that the fitness of a tall building for occupancy depends not only on its structural condition, but also the functionality of key nonstructural components including elevators, smoke evacuation systems, fire sprinklers and alarms, plumbing and lighting. This guideline does not cover the design of these nonstructural features, but rather, assumes that as a minimum, these components and systems will be designed and installed in accordance with the requirements of the applicable building code. If building structural design results in response likely to lead to increased susceptibility of these critical nonstructural components to failure, alternative means to protect these critical systems should be considered in the design.

## 7.5 Structural Modelling

### 7.5.1 Modeling Dimension

Conduct analyses using a three-dimensional mathematical model of the physical structure that represents the structure's spatial distribution of the mass and stiffness to an extent that is adequate for the calculation of the significant features of the building's linear dynamic lateral response.

**Commentary:** Three-dimensional mathematical models of the structure are required for all analyses and evaluations. Given the current state of modeling capabilities and available software systems, there is no reason to estimate the actual three-dimensional behavior of tall buildings by relying on approximate two-dimensional models. The accuracy obtained by using three-dimensional models substantially outweighs the advantage of the simplicity offered by two-dimensional models.

**Table 7-1. Expected Material Strengths**

Material	Expected Strength
Structural steel	
Hot-rolled structural shapes and bars	
ASTM A36/A36M	$1.5F_y$
ASTM A572/A572M Grade 42 (290)	$1.3F_y$
ASTM A992/A992M	$1.1F_y$
All other grades	$1.1F_y$
Hollow Structural Sections	
ASTM A500, A501, A618 and A847	$1.3F_y$
Steel Pipe	
ASTM A53/A53M	$1.4F_y$
Plates	$1.1F_y$
All other products	$1.1F_y$
Reinforcing steel	1.17 times specified $f_y$
Concrete	1.3 times specified $f'_c$

**Table 7-2. Effective Component Stiffness Values**

Component	Flexural Rigidity	Shear Rigidity	Axial Rigidity
Structural steel Beams, Columns and Braces	EI	GA	EA
Composite Concrete Metal Deck Floors	$0.5E_cI_g$	$G_cA_g$	$E_cA_g$
R/C Beams -- nonprestressed	$0.5E_cI_g$	$G_cA_g$	$E_cA_g$
R/C Beams -- prestressed	$E_cI_g$	$G_cA_g$	$E_cA_g$
R/C Columns	$0.5E_cI_g$	$G_cA_g$	$E_cA_g$
R/C Walls	$0.75E_cI_g$	$G_cA_g$	$E_cA_g$
R/C Slabs and Flat Plates	$0.5E_cI_g$	$G_cA_g$	$E_cA_g$

### 7.5.2 Material Stiffness and Strength

Structural models shall incorporate realistic estimates of stiffness and strength considering the anticipated level of excitation and damage. Use expected, as opposed to nominal or specified properties except when calculating the capacity of brittle elements where specified strength values shall be used.

In lieu of detailed justification, values provided in Tables 7-1 and 7-2 may be used for expected material strengths and estimates of component stiffness, respectively.



7.5.3 Torsion

The mathematical model shall address torsional behavior of the structure. Inherent eccentricities resulting from the distribution of mass and stiffness shall be considered. Accidental eccentricities need not be considered for serviceability evaluation.

7.5.4 Beam-column Panel Zones

In lieu of explicit modeling of beam-column panel zone behavior, center-to-center beam dimensions may be used.

7.5.5 Floor Diaphragms

Floor diaphragms must be explicitly included in the mathematical model of the building using realistic strength and stiffness properties unless clear and convincing evidence is presented to substantiate full rigidity or full flexibility of floors relative to relevant vertical lateral load resisting system(s). Regardless of the relative rigidity or flexibility of floor diaphragms, floors with significant force transfer (i.e., podium effect, etc.) and floors immediately above and below such floors shall be explicitly included in the mathematical model. Diaphragm chord and drag forces shall be established in a manner consistent with the floor characteristics, geometry, and well established principles of structural mechanics. Both shear and bending stresses in diaphragms must be considered. At diaphragm discontinuities, such as openings and reentrant corners, the dissipation or transfer of edge (chord) forces combined with other forces in the diaphragm must be within shear and tension capacity of the diaphragm. Collectors shall be provided that are capable of transferring the seismic forces originating in other portions of the structure to the element providing the resistance to those forces.

7.5.6 Foundation-Soil Interface

Soil-foundation-structure interaction analysis is not required for serviceability evaluation. However, the model shall extend to the base mat. Refer to Chapter 5 for additional discussion.

**Commentary:** Detailed soil-structure interaction is complex and time consuming and is not necessary for service level evaluations where simple yet generally conservative assumptions suffice.

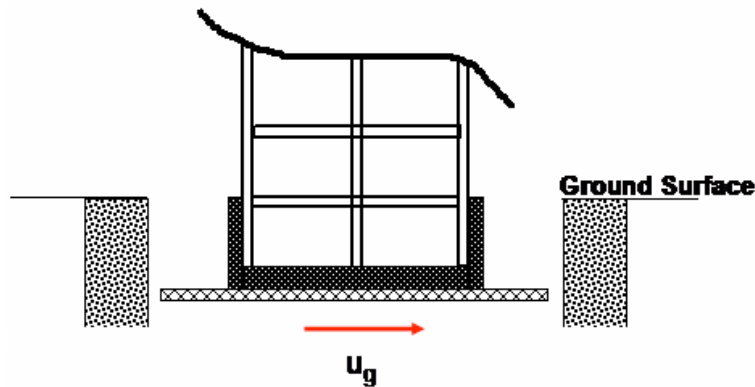
7.5.7 Subterranean Levels

The analytical model of the structure:

- (1) shall include the entire building including the subterranean levels (i.e., floors, columns, walls, including the basement walls);
- (2) shall include the mass and mass moment of inertia of the subterranean levels

- (3) may ignore the horizontal effect of soil surrounding the subterranean levels, and
- (4) may assume rigid soil beneath the foundations (i.e., no vertical soil springs).

**Commentary:** The simple modeling technique represented here is intended to be used with the surface level ground motions. Therefore, the free-field design spectra defined in section 7.2. shall not be reduced by either changing the soil site conditions to subgrade soil conditions or by inclusion of kinematic or inertial interaction between soil and structure.



**Figure 7.1 Sketch of simplified model for the building and subterranean levels.**

#### 7.5.8 Column bases

Column bases may be considered pinned for displacement and drift calculations. A column base may be considered fixed if the column base connection to the foundation is capable of transferring axial forces and deformations to the foundation with negligible joint rotation.

### 7.6 Design Parameters

Evaluate roof displacement, story drifts, and member forces (axial, flexure, shear, and torsion).

#### 7.6.1 Load Combinations

Evaluate the structure for the following load combinations. Alternative load combinations, if used, shall be adequately substantiated.

$$1.0D + L_{exp} \pm 1.0E_x \pm 0.3E_y$$

$$1.0D + L_{exp} \pm 1.0E_y \pm 0.3E_x$$

## 7.6.2 Response Modification Factors

Code response modification factors do not apply to serviceability evaluation (i.e.,  $R$ ,  $\Omega_0$ ,  $\rho$ ,  $C_d$ , are all taken as unity).

## 7.7 Acceptance Criteria

### 7.7.1 Forces

For structural steel components the maximum combined stress ratios shall not exceed the applicable LRFD values using specified material properties and corresponding load and resistance factors as specified in governing prescriptive building code provisions. For reinforced concrete components the maximum combined forces (axial, flexure and shear) shall not exceed the applicable ACI-318/08 strengths using specified material properties and applicable ACI-318/08 reduction factors,

**Exception:** Up to 20% of members designed to behave in a ductile manner may exceed these acceptance criteria for ductile actions such as flexure in confined or compact members or shear in properly detailed steel shear links as long as none of these members exceed the criteria by more than 50% and such exceedance does not affect the overall performance of the building.

### 7.7.2 Displacements

The maximum calculated racking inter-story drift ratios shall not exceed the permitted values denoted in Table 7-3.

**Table 7.3. Maximum Permitted Elastic Racking Interstory Drift Ratios**

<i>Structural System</i>	<i>Permitted Maximum Value</i>
Special Moment Resisting Frames	0.010
Special Concentric Braced Frames	0.005
Eccentric Braced Frames	0.005
Unbonded Braced Frames	0.0075
Special Steel Plate Shear Walls	0.005
R/C Shear Walls	0.005

**Commentary:** Lateral displacements of tall buildings can be considered as the sum of displacements in several modes: racking or frame action, cantilever action, shear-leak and beam-column panel zone distortions (Naeim 2001). Drift results reported by analysis include the contribution of each of these several modes. Racking action can be directly related to damage potential while the drift caused by cantilever action does not necessarily cause damage. Shear-leak deformations are generally small and panel zone distortions are approximated for

- 1 *serviceability evaluation by using center-to-center dimensions. The drift limits*
- 2 *provided in Table 7-3 may be obtained from the analytical model by deducting*
- 3 *deformation caused by cantilever action from the total computed deformation.*

4

## 8 MAXIMUM CONSIDERED RESPONSE EVALUATION

### 8.1 Objective

The objective of the Maximum Considered response evaluation is to provide implicitly adequate safety against collapse. This objective is achieved by evaluating the response of the structure to ground motions that represent Maximum Considered Earthquake shaking as defined in Chapter 21 of ASCE-7.05 and Chapter 5 of this guideline. This response evaluation does not provide a quantifiable margin against (or a probability of) collapse, but is intended to demonstrate that collapse under the selected ground motions does not occur, i.e., the structure maintains stability, and forces and deformations are within acceptable limits.

**Commentary:** *The capability exists to predict the ground motion intensity at which collapse occurs, as well as the probability of collapse given the ground motion intensity (ATC 2008, Zareian and Krawinkler 2007). But the process of collapse prediction is complex and is based on the presumption that the force-deformation characteristics of all important structural components can be modeled for the full range of deformations associated with inelastic behavior leading to collapse. At this time insufficient knowledge exists to model such behavior with confidence for all the types of structural components that might be utilized in tall buildings. Until such knowledge is developed the stability evaluation recommended in this section is the preferred method for providing adequate safety against collapse.*

### 8.2 Design and Evaluation Process

#### 8.2.1 Design Considerations

Structural system and component selection and layout should pay careful attention to capacity design considerations. The target should be to pre-select zones and behavior modes in which ductility (large inelastic deformation capacity) can be provided through proper detailing, and to tune the structural system such that response evaluation will confirm that: 1) inelastic deformations are indeed concentrated in these zones; 2) inelastic behavior is in desirable behavior modes and 3) excessive force and deformation demands for undesirable behavior modes (such as large shear forces in columns) are prevented.

Desirable behavior modes include, but are not limited to the following:

- Flexural yielding in beams, slabs shear wall piers and coupling beams
- Tension yielding in diagonally reinforced coupling beams
- Tension yielding in steel braces and steel plate shear walls, and tension/compression yielding in buckling restrained braces
- Post-buckling compression in braces that are not essential parts of the gravity load system
- Shear yielding in steel components (e.g., panel zones in moment frames, shear links in EBFs, steel coupling beams)

- Yielding in ductile fuses or energy dissipation devices
- Controlled rocking of foundations

In zones of intended inelastic behavior it is imperative to provide ductile detailing that assures inelastic deformation capacity prior to deterioration in strength.

For behavior modes in which inelastic deformation capacity cannot be assured (force-controlled actions) it is essential to avoid overloads that exceed the reliable force capacity and to protect, through appropriate detailing, against unexpected brittle failure modes (such as fracture in steel moment connections or gusset plate to frame connections in braced steel frames).

**Commentary:** Tall buildings are complex dynamic systems and in many cases it will not be possible to identify up front all zones in which inelastic deformations will be concentrated. Nonlinear dynamic analysis will disclose whether or not the pre-selected zones are indeed the only ones in which inelastic deformations are concentrated. An important goal of the response evaluation process is to identify all regions of potential inelastic behavior, whether or not they have been targeted up front as zones of desired inelastic behavior. For this reason the term “capacity design” has to be used with caution in the design of tall buildings. A typical example of “non-targeted zones” of inelastic behavior is flexural yielding in mid- or even upper stories of shear walls, which often is caused by higher mode effects. If such yielding is observed in the response evaluation, then these “non-targeted zones” zones have to be detailed appropriately for ductility.

Except when specifically exempted, design for strength and ductility should conform to all criteria specified in the most recent material codes and specifications and referenced in the most recent ASCE-7 edition.

If non-standard materials or components are utilized as part of the structural system, sufficient documentation should be provided to justify all assumptions on which the computation of strength and deformation capacities is based. The Structural Peer Review should evaluate the adequacy of the provided information and assumptions.

In the context of design for force and deformation demands, the following structural components and elements require special attention:

- Diaphragms and collectors
- Components and elements affected by podium/backstay effects
- Opening in walls
- Outrigger systems
- Locations of abrupt change in lateral stiffness or mass
- Gravity framing system, unless it is considered part of the lateral load resisting system

## 8.2.2 Evaluation Criteria

Section 8.3 provides analysis recommendations to predict structural response to Maximum Considered Earthquake shaking. Sections 8.4 and 8.5 present recommendations for structural modeling. Section 8.6 presents criteria for evaluating the adequacy of response at a component level.

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In addition to evaluation of the performance of individual structural components, system performance should be evaluated based on maximum transient and residual story drifts and the ability of the structure to resist the imposed ground motions without a significant loss of strength. The average (mean) of the absolute values of peak transient drift ratios in each story from the suite of analyses should be less than 0.03, and the average of the absolute values of residual drift ratios in each story from the suite of analyses should be less than 0.01. The maximum story drift ratio in any analysis anywhere in the structure should not exceed 0.045 nor should the maximum residual story drift ratio in any analysis exceed 0.015 unless justification is provided and accepted by the Peer Review. Cladding systems, including the cladding itself and its connections to the structure, should be capable of accommodating at least the mean of the absolute values of the peak transient story drifts in each story.

**Commentary:** *The use of a story drift limit of 0.03 has shown to result in good and efficient designs in recent tall building projects. There is general consensus that up to this story drift structures with good detailing will perform well (without significant loss of strength), and that properly attached nonstructural components will not pose a major life safety hazard. The drift limit should be applied to the "total" story drift (caused by story racking and story flexural rotation) because it is intended to protect all components of the structure including the gravity system components that are surrounding shear walls or braced frames and are subjected mostly to a story shear (racking) mode of deformations. A story drift limit of 0.03 also provides P-Delta control in stories with large vertical loads. The residual story drift ratio of 0.01 is intended to protect against excessive post-earthquake deformations that likely will cause condemnation or excessive downtime for the building. This criterion is added to provide enhanced performance for tall buildings.*

*The suggested maximum transient drift of 0.045 has been selected judgmentally based on the authors understanding of the limits beyond which structural analysis using present day tools loses reliability. Similarly, the limit on maximum residual drift of 0.015 has been selected judgmentally because of a concern that tall buildings with residual drifts in excess of this amount may pose substantial hazards to surrounding construction in the event of strong aftershocks. In each case, these limits are to be evaluated against the maximum response predicted in any of the response histories. It may be acceptable to accept drifts that are larger than this amount, if the Peer Review agrees either that the large predicted response is due to peculiarities in the ground motion characterization, that may not be fully appropriate, or agreement that the structure's response is reliably predicted and acceptable, even given the large predicted drifts.*

*When evaluating peak transient drifts, the maximum absolute value of the drift in each story from each of the analyses in the suite should be used to determine the mean drift, rather than by taking the mean of the maximum drift in the positive direction, and the maximum drift in the negative direction separately. This is because the phasing of ground motion is unpredictable and has equal likelihood of producing large positive drift as it does large negative drift.*

## 8.3 Loads and Response Prediction

### 8.3.1 Seismic Input

Analyze the structure should for a minimum of seven pairs of ground motions, selected and matched to the target spectrum in accordance with the recommendations of Chapter 5.

A ground motion pair is represented by accelerograms in two orthogonal horizontal directions. The pair of accelerograms should be applied in the structure's principal directions, unless near-fault directionality effects dominate the ground motion in which case the accelerograms should be applied in the fault-parallel and fault-normal directions.

Ground motion selection and scaling should follow the criteria given in Chapter 5 for the Maximum Considered Earthquake shaking level. The accelerograms should be applied at locations that represent the interface between the structure and the soil, as defined in Chapter 5, with appropriate attention given to modeling of soil-structure interaction.

The seismically effective masses should be derived from the full dead loads, including appropriate contributions from partitions and other transient loads that might contribute to amplifying structural response.

### 8.3.2 Contributions of Gravity Loads

The following gravity loads should be applied as initial conditions in the analysis:

$$1.0D + L_{\text{exp}}$$

A default value of  $0.25L$  ( $L$  is the unreduced live load) may be used for  $L_{\text{exp}}$ , unless case specific conditions demand a larger value (e.g., storage loads) or justify a smaller value.

**Commentary:** *Nonlinear analysis is load path dependent, i.e., the results depend on combined gravity and lateral load effects. The gravity load applied in the analysis should be equal to the expected gravity load. The dead load should include the structure's self weight, architectural finishes (partitions, exterior wall, floor and ceiling finishes), and an appropriate allowance for mechanical and electrical services and equipment. For overall system response of tall buildings, the live load should be reduced from the nominal design live load to reflect: 1) the low probability of the full design live load occurring simultaneously throughout the building, and 2) the low probability that the design live load and Maximum Considered earthquake shaking will occur simultaneously.*

### 8.3.3 Response Prediction Method

Perform nonlinear response history analysis (NRHA) using a three-dimensional model of the soil-foundation-structure system to predict all seismic demands. Chapter 5 presents recommendations for modeling soil-structure interaction.

**Commentary:** *Nonlinear static procedures (various options of pushover analysis) may be useful as a design aid, but should not be relied upon to quantify response*



characteristics for tall buildings. They may produce results of unknown reliability depending on the option used, and in general are unable to reproduce phenomena that are a consequence of significant inelastic redistribution, such as shear force amplification in shear walls caused by flexural plastic hinging at the base of the wall. There is much intrinsic value to a pushover analysis (for instance it permits graphical representation and visualization of progression of inelastic behavior) and can assist in identifying the primary modes of inelastic behavior under first mode response. However, in many practical cases such an analysis is not capable of capturing the effects of variations in the frequency content of the ground motions and of variations in higher mode effects.

#### 8.4 System Modelling

A three-dimensional model of the soil-foundation-structure system should be developed, which represents all components and force and deformation characteristics that significantly affect the prediction of seismic demands at the Maximum Considered response level. The implication is that components and force or deformation characteristics that do not significantly affect important demands can be ignored. This might apply to components of the foundation system, its interface with the soil, or to the superstructure.

**Commentary:** Good engineering knowledge and judgment are needed to make these decisions. For instance, if adequate safeguards are taken against excessive shear deformations and shear failure in reinforced concrete components (walls, beams and columns) through the use of appropriate capacity design concepts, then simulation of shear deformations might not be warranted. But such decisions will require a careful review of analysis results to verify that the analysis assumptions made are indeed justified, and might require post-analysis strengthening or a re-analysis if the assumptions made are shown to be incorrect.

Evaluate force and deformation demands for all components and elements that form an essential part of the lateral and gravity load path and the failure of which might affect the stability of the structure during and after Maximum Considered Earthquake shaking. Explicitly incorporate in the analysis model components and elements of the gravity load-resisting system that contribute significantly to lateral strength and stiffness. For all components, elements, and connections not included in the analysis model a compatibility check should be performed at maximum story drifts predicted by analysis in order to assure that these parts of the structure will maintain their gravity load resistance and will not cause stability problems.

In modeling "damping" it should be considered that most hysteretic energy dissipation is explicitly incorporated in the hysteresis model and cannot be used to justify an increase in effective viscous damping for nonlinear analysis.

**Commentary:** Damping effects of structural members that are not incorporated in the analysis model (e.g., gravity framing), foundation-soil interaction, and nonstructural components that are not otherwise modeled in the analysis can be incorporated through equivalent viscous damping. The amount of viscous damping should be adjusted based on specific features of the building design and may be represented by either modal damping, explicit viscous damping elements, or a combination of stiffness and mass proportional damping (e.g.,

*Rayleigh damping). Section 2.4 of ATC (2009) provides a discussion and recommendations for modeling viscous damping in analytical models of tall building structures.*

The analysis model should be capable of representing the flexibility of the floor diaphragms as deemed necessary to realistically simulate distribution of inertia forces to the various vertical elements and to produce information for strength design of diaphragms and collector elements.

**Commentary:** Chapter 5 of ATC (2009) provides recommendations for modeling of diaphragms and collectors.

The analysis model should be capable of representing “podium and backstay effects” caused by locking vertical elements (e.g., shear walls or braced or moment frames) between diaphragms that are supported by stiff vertical elements such as exterior basement walls.

**Commentary:** Because of the large in-plane stiffness of the diaphragms and the supporting stiff vertical elements, the locked vertical element may experience a drastic change in shear force and overturning moment below the diaphragm(s) supported by exterior walls. The change in shear force and overturning moment demands will depend strongly on the in-plane stiffness and strength of the diaphragm and its supporting elements, as well as on the foundation type below the podium structure. Perhaps most important are the relative stiffness values. Realizing that these stiffness values depend on the extent of cracking, it might be necessary to make bounding assumptions on stiffness properties in order to bracket the forces for which the various components of the podium structure have to be designed. Chapter 5 of ATC (2009) provides recommendations for modeling of the podium and backstay effects.

Represent P-Delta effects in the analytical model, whether or not elastic concepts indicate that such effects are important.

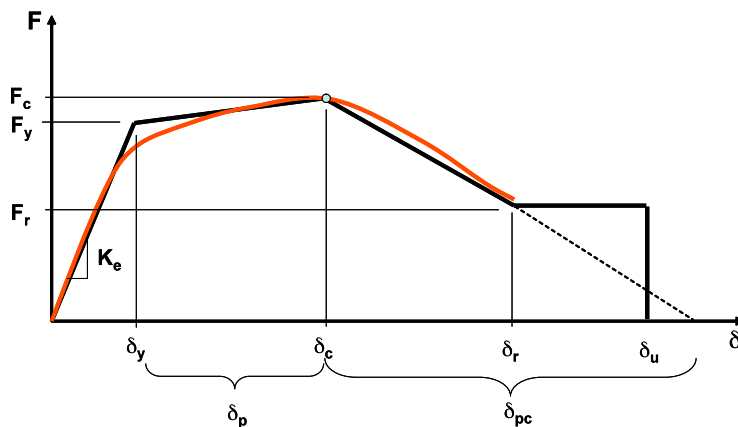
**Commentary:** The widely used elastic stability coefficient ( $\theta = P\delta/Vh$ ) is often an insufficient indicator of the importance of P-Delta effects in the inelastic range. P-delta effects may become an overriding consideration when strength deterioration sets in and the tangent stiffness of the story shear force – story drift relationship approaches zero or becomes negative. When this happens, the story drift ratchets, i.e., it increases in one direction without the benefit of a full reversal that otherwise would straighten out the story. For this reason, and many others, realistic modeling of component deterioration and post-yield stiffness are critical aspects of modeling. The potential for dynamic instability is relatively high in flexible moment frame structures and in braced frames and shear wall structures in which one or several of the lower stories deform in a shear mode and the tributary gravity loads are large so that P-Delta will lead to a significant amplification of story drift demands. Section 2.3 of ATC (2009) provides detailed information on P-Delta effects and why and when it becomes an important consideration in the inelastic response of structures.

## 8.5 Structural Component Modelling

### 8.5.1 Important Modeling Parameters

It is necessary to employ hysteretic models that incorporate all important phenomena contributing to demand prediction as the structure approaches collapse. Such models should be capable of simulating (a) monotonic response beyond the point at which maximum strength is attained, (b) hysteretic properties characterizing component behavior without the effect of cyclic deterioration, and (c) cyclic deterioration characteristics.

**Commentary:** There are many alternatives for describing these component characteristics. Presented here is the alternative discussed in detail in Section 2.2 of ATC (2009). Monotonic response may be characterized by a multi-linear diagram of the type shown in Fig. 8.1 (refinements such as a distinction between pre- and post-cracking stiffness before component yielding are desirable but in most cases not necessary for Maximum Considered Earthquake response evaluation). This monotonic response curve is referred to here as the monotonic backbone curve. It is described by the parameters shown in Fig. 8.1 and represents the theoretical component force-deformation behavior, if the component is pushed in one direction, without cycling, to failure.



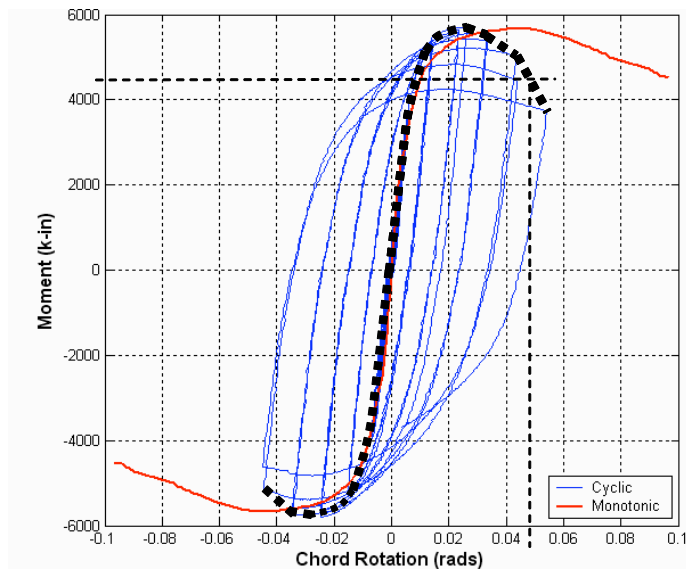
- Effective yield strength and deformation ( $F_y$  and  $\delta_y$ )
- Effective elastic stiffness,  $K_e = F_y / \delta_y$
- Strength cap and associated deformation for monotonic loading ( $F_c$  and  $\delta_c$ )
- Pre-capping plastic deformation for monotonic loading,  $\delta_p$
- Effective post-yield tangent stiffness,  $K_p = (F_c - F_y) / \delta_p$
- Post-capping deformation range,  $\delta_{pc}$
- Effective post-capping tangent stiffness,  $K_{pc} = F_r / \delta_{pc}$
- Residual strength,  $F_r = \kappa F_y$
- Ultimate deformation,  $\delta_u$

**Figure 8.1 Monotonic backbone curve parameters**

Basic hysteresis rules could follow preselected rules, such as bilinear, peak oriented, or pinched hysteresis rules. Cyclic deterioration can be described by a cyclic deterioration parameter, such as the energy based parameter discussed in Section 2.2.4 of ATC (2009).

The effect of cyclic deterioration is that the point of maximum strength (capping point) moves closer to the origin, i.e., both the peak strength that can be achieved and the deformation at which peak strength is realized become smaller with successive cycles. The amount that the peak strength and deformation at which peak strength is attained move with increasing cycles depends on the loading history.

It is important to note that there is a clear difference between the monotonic backbone curve such as that shown in Figure 8-1 and a cyclic envelope curve obtained by enveloping the peaks of a cyclic response history (Section 2.2.4 of ATC (2009)) such as shown in Figure 8-2. The monotonic curve will exhibit greater deformation capacity and reduced post-peak strength negative stiffness, relative to the envelope curves obtained from typical cyclic component tests.



**Figure 8-2 Typical Monotonic Backbone Curve and Cyclic Envelope Curve**

### 8.5.2 Methods for Computing Component Properties

The properties of the component backbone curve and of cyclic deterioration characteristics may be obtained from a combination of appropriate analytical approaches and experimental observations. In order to obtain these properties, the following deterioration modes should be considered (this list is incomplete), unless these modes are prevented up front through proper detailing:

For structural steel components

- Member buckling in compression elements

- 1 • Local buckling of flanges or web of beams or columns
- 2 • Lateral torsional buckling of beams or columns
- 3 • Ductile tearing in base material
- 4 • Crack propagation and fracture at weldments, net sections, or gusset plates
- 5 • Bolt slippage in connections
- 6 • Bolt yielding and bearing at connections
- 7 • Block shear in connections
- 8 • Prying action in connections
- 9 • Gusset plate bending and buckling
- 10 • Shear buckling of plates (e.g., in EBF links or joint panel zones)
- 11 For reinforced concrete components
- 12 • Concrete tensile cracking, crushing, and spalling
- 13 • Rebar buckling and fracture
- 14 • Bond slip
- 15 • Loss of anchorage of reinforcement
- 16 • Prying (dowel) action
- 17 • Reduction in confinement due to yielding and fracture of confinement
- 18 reinforcement
- 19 • Reduction in aggregate interlock
- 20 • Diagonal tension cracking
- 21 • Horizontal shear cracking
- 22 • Sliding at cracked interfaces and at construction joints
- 23 Strength properties of the component backbone curve should be based on expected
- 24 material strengths. In lieu of detailed justification, values provided in Table 7-1 may be
- 25 used for expected material strengths.
- 26 Methods for obtaining component properties include detailed continuum finite element
- 27 models, curvature and fiber models, and experiment-based phenomenological models.
- 28 The appropriate choice depends on many considerations, including the following:
- 29 • Continuum finite element models are usually appropriate provided that cyclic
- 30 material properties and the aforementioned deterioration/failure modes are
- 31 adequately simulated. The cost of analysis is prohibitive in most practical
- 32 applications.
- 33 • Curvature and fiber models are appropriate provided all important deterioration
- 34 modes can be simulated adequately. Great difficulties are often encountered in
- 35 simulating deterioration due to local and lateral torsional buckling in steel
- 36 components, and rebar buckling, bond slip, and shear deformations in reinforced
- 37 concrete components. Thus, the use of such models often necessitates the
- 38 specification of artificial limits to simulate these often critical deterioration modes.
- 39 It is inappropriate to ignore these deterioration modes in curvature and fiber

models. In cases of important bi-axial load effects (e.g., many columns and shear wall configurations) such models may present the only viable alternative. However, models of this type need to be validated through experimental results in order to capture, through strain limits or other means, limit states beyond which severe deterioration is likely and no reliance can be placed on a reproduction of response.

- Phenomenological modeling usually implies the use of concentrated hinge models whose properties are determined from principles of engineering mechanics and are calibrated by means of experimental data. This requires the availability of experimental databases that can be employed to calibrate a phenomenological model for a wide range of parameters. Several extensive databases are available for steel and reinforced concrete beam and column components and have been used to calibrate parameters for the generic deterioration model discussed in Section 8.5.1. Point hinge models are difficult to implement in components subjected to bi-axial bending (many columns and shear wall configurations) and large variations in axial force.

### 8.5.3 Options for Component Analytical Models

Deformation capacities may be taken equal to the corresponding Primary Collapse Prevention values published in ASCE 41 (with Supplement 1) for nonlinear response procedures, unless different values can be justified based on analytical models validated by experimental evidence. When applicable, the ASCE 41 component force versus deformation curves may be used as modified backbone curves, with the exception that the drop in resistance following the point of peak strength should not be as rapid as indicated in the ASCE 41 curves. Such a rapid drop is not realistic (unless fracture occurs) and is likely to cause numerical instabilities in the analysis process. Alternatively, the modeling options presented in ATC (2009) may be employed.

Component models that account neither for post-capping strength deterioration nor for cyclic deterioration should not be used for Maximum Considered Earthquake response evaluation, unless appropriate limitations on the maximum deformation are specified and no credit is given to undefined strength properties beyond this level of deformation.

**Commentary:** Section 2.2.5 of ATC (2009) proposes the following four options for component analytical models.

Option 1 – explicit incorporation of cyclic deterioration in analytical model: This option explicitly incorporates post-capping strength deterioration and cyclic deterioration in the analytical model, by using the monotonic backbone curve as a reference boundary surface that moves “inward” (towards the origin) as a function of the loading history. This is the preferred option.

Option 2 – use of a cyclic envelope curve as a modified backbone curve; cyclic deterioration is not considered explicitly. If the cyclic envelope curve is known (e.g., from a cyclic test that follows a generally accepted loading protocol) then it is acceptable to use this envelope curve as the modified backbone curve for analytical modeling and ignore additional cyclic deterioration - provided that no credit is given in the analysis to undefined strength characteristics beyond the bounds established by the cyclic envelope curve, i.e., the ultimate deformation  $\delta_u$  in any analysis should be limited to the maximum deformation recorded in the cyclic test. When using this approximation, one must make sure to include the

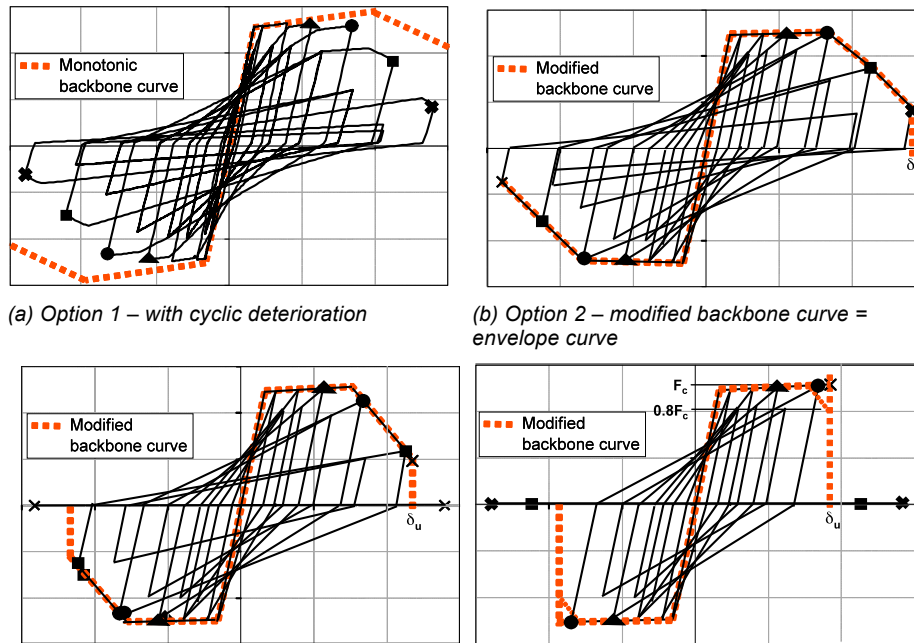
negative tangent stiffness portion of the cyclic envelope curve as part of the modified backbone curve of the analytical model.

Option 3 – use of factors for modification of backbone curve; cyclic deterioration is not considered explicitly: If only the monotonic backbone curve is known (or predicted) and cyclic deterioration is not incorporated in the analytical model, then the shape of the backbone curve must be modified to account approximately for cyclic deterioration effects. Numerical values of the modification factors might depend on material, configuration, and detailing of the structural component. Until more accurate and component specific data becomes available, it is recommended to use the following values for the modified backbone curve:

- Strength cap  $F_c'$ : 0.9 times the monotonic backbone curve value  $F_c$
- Pre-capping plastic deformation  $\delta_p'$ : 0.7 times the monotonic backbone curve value  $\delta_p$
- Post-capping deformation range  $\delta_{pc}'$ : 0.5 times the monotonic backbone curve value  $\delta_{pc}$
- Residual strength  $F_r'$ : 0.7 times the monotonic backbone curve value  $F_r$
- Ultimate deformation  $\delta_u'$ : 1.5 times  $\delta_c$  of the monotonic backbone curve.

Option 4 – no deterioration in analytical model: If the post-capping (negative tangent stiffness) portion of the modified backbone curve of option 2 or 3 is not incorporated in the analytical model (i.e., a non-deteriorating model is employed), then the ultimate deformation of the component should be limited to the deformation associated with 80% of the strength cap on the descending branch of the modified backbone curve as obtained from option 2 or 3. No credit should be given in analysis to undefined strength characteristics beyond this deformation limit.

Figure 8.3 illustrates the four options for a typical experimental cyclic loading history and a peak-oriented hysteresis model. Several equivalent points of equal peak displacement for the four options are identified with symbols. The differences appear to be small, but primarily because the illustrations are for a symmetric and step-wise increasing loading history, which is typical for experimental studies but not for response at the Maximum Considered Earthquake shaking levels. As intended, the larger the simplification the more the inelastic deformation capacity is being reduced. This is most evident in Figs. 8.2(c) and (d), in which the attainment of the estimated  $\delta_u$  limits the inelastic deformation capacity.



**Figure 8.3 Illustration of implementation of the four options for analytical component modeling**

The choice of an appropriate component modeling option and of the basic hysteresis model used to represent the cyclic response of structural components needs to be justified and become part of the analysis documentation.

#### 8.5.4 Specific Component Modeling Issues

##### 8.5.4.1 Steel beams and columns in bending.

The rotation values provided in Section 3.2 of ATC (2009) may be employed as an alternative to the rotation values given in ASCE 41. These values are based on the assumption that point hinge models are used to represent inelastic flexural behavior and that one of the four analytical modeling options summarized in the commentary to Section 8.5.3 is utilized. The deformation values given in ATC (2009) are for the monotonic backbone curve illustrated in Fig. 8.1 and need to be modified unless modeling option 1 is utilized. The ATC (2009) values may also be applied to "Fully Restrained Moment Connections". It is recommended not to use the ASCE 41 Table 5-6 plastic rotation angles for "Beams – Flexure" and "Column – Flexure" as these large values are not confirmed through available experimental data.

**Commentary:** One important conclusion drawn from the ATC (2009) data and proposed parameters is that for steel beams the pre-capping plastic rotation ( $\theta_c$ )



1 *is relatively small (on the order of 2%) but the post-capping deformation ( $\theta_{pc}$ ) is*  
2 *large, i.e., the decrease in strength after peak strength is slow.*

3 *Very few experimental data are available for rotation values for plastic hinging in*  
4 *columns. Until such data becomes available, low values for  $\theta_c$  and  $\theta_{pc}$  should be*  
5 *used, with the maximum assumed values not being larger than those given for*  
6 *beams in Section 3.2 of ATC (2009).*

#### 7 8.5.4.2 Steel beam-column joint panel zones

8 Experimental evidence indicates that deterioration in the shear force – shear distortion  
9 response of a joint panel zone is small unless shear buckling occurs. The latter mode is  
10 unlikely to occur because of code detailing criteria. Thus, it should be acceptable to  
11 neglect deterioration in the modeling of joint panel zones, unless there is clear indication  
12 that deterioration will occur within the range of deformations expected at maximum  
13 considered response levels.

14 The effect of panel zone distortion on the plastic rotation capacity of fully restrained  
15 moment connections should be considered in modeling of the flexural behavior of  
16 beams.

17 Modeling rules for panel zone behavior are presented in Section 3.3 of ATC (2009).

#### 18 8.5.4.3 Steel EBF link beams

19 Plastic deformation values should be based on experimental evidence, particularly if  
20 non-standard boundary conditions are employed. When applicable, the values listed in  
21 Table 5-6 of ASCE 41 may be utilized.

#### 22 8.5.4.4 Steel coupling beams

23 Provided that the full strength of the coupling beam can be developed through  
24 anchorage into the wall, the plastic deformation values for eccentric braced frame links  
25 should be applicable to steel coupling beams in walls. Depending on the anchorage into  
26 the shear wall, the need may exist to provide additional rotational springs at the ends to  
27 account for relative rotation between the coupling beam and the shear wall.

#### 28 8.5.4.5 Steel axially loaded components

29 Important modeling issues are post-buckling deterioration, ductile tearing due to  
30 localized strain reversal during post-buckling cyclic loading, and fracture at connections.  
31 The latter needs to be treated separately from component modeling. Post buckling  
32 modeling and ductile tearing depend strongly on brace section and slenderness ratio.  
33 Recent references on these deterioration and failure modes are Jin and El-Tawil (2003),  
34 Uriz (2005), Uriz et al (2008), Fell et al. (2006), Fell (2008).

35 Braces in frame configurations and in outriggers depend strongly on the ability of the  
36 connections to transfer pre- and post-buckling forces from the brace to horizontal and  
37 vertical chord members. Additional strain may be placed on the connection by relative  
38 rotations of the chord members at the brace intersections. It is of paramount importance  
39 to consider all conceivable failure modes at the brace connection when assigning  
40 strength and deformation parameters to the bracing member.

#### 8.5.4.6 Steel plate shear walls

Important modeling issues are effective story shear strength and stiffness, including the pinching effect caused by tension field reversal, and deterioration due to connection failures and possibly due to combined bending and axial load effects in the vertical boundary elements. If cyclic strip models are used, a sufficient number of strips must be used to adequately simulate the column bending moments due to force transfer between the shear wall panel and the vertical boundary elements. At large story drifts the combined bending and axial load capacity of the vertical boundary elements might deteriorate due to shear racking that causes large localized rotations in these boundary elements. P-Delta might become a critical issue if the shear wall deforms in a shear racking mode that concentrates inelastic deformations in the lower stories. Information on modeling of steel plate shear walls can be found in *AISC (2006)* and in the many references listed in that publication.

#### 8.5.4.7 Reinforced concrete beams and columns in bending

The values provided in Section 3.4 of *ATC (2009)* may be employed as an alternative to the rotation values given in *ASCE 41* (including Supplement 1). These values are based on the assumption that point hinge models are used to represent inelastic flexural behavior and that one of the four analytical modeling options summarized in the commentary to Section 8.5.3 is utilized. The deformation values given in *ATC (2009)* are for the monotonic backbone curve illustrated in Fig. 8.1 and need to be modified unless modeling option 1 is utilized.

**Commentary:** *The rotation values in Section 3.4 of ATC (2009) are in many cases significantly larger than those listed in ASCE 41. The reasons are (1) bond slip at the beam-column interface contributes significantly to plastic rotations, (2) the listed plastic rotations are for the monotonic backbone curve and would have to be modified (by a recommended factor of 0.7) for comparison with the ASCE 41 values, and (3) the listed values are expected values whereas the ASCE 41 values represent a lower percentile value.*

*The ATC (2009) values have been derived from a database that contains mostly experimental results from column tests. The regression equations have been extrapolated to an axial load of zero in order to be applicable for beams. This process may not be fully justified because beams have unequal longitudinal top and bottom reinforcement and no distributed side face reinforcement, and in most cases have contributions from a slab system. Guidance for modeling slab contributions can be found in NEHRP (2008).*

The elastic stiffness used in the analytical model may have some effect on the computed maximum considered response demands. Values for an effective elastic stiffness are given in *ASCE 41 Supplement 1*, and somewhat different values are recommended in Section 3.4 of *ATC (2009)*. The effect of the different stiffness assumptions is not believed to be important in the prediction of deformation demands for beams and columns, i.e., either the *ASCE 41* or the *ATC (2009)* recommendations should be adequate.

#### 8.5.4.8 Reinforced concrete beams and columns in shear

Beams and columns should be protected from excessive shear deformations through capacity design requirements. But flexural plastic hinging might reduce the shear

1 strength to the extent that inelastic shear deformation possibly will occur. In such cases  
2 a shear force – shear deformation model (usually a translational spring) should be  
3 inserted in the element. Recommendations for modeling shear strength, stiffness and  
4 deformation capacity are provided in *ASCE 41*, including *Supplement No. 1*.

#### 5 8.5.4.9 Reinforced concrete slabs in slab-column frames

6 Recommendations for the effective width and stiffness properties of slabs in slab-column  
7 frames are provided in Section 4.6 of *ATC (2009)*. Compatible recommendations are  
8 given in Supplement 1 of *ASCE 41*. Rotational springs should be used to model  
9 torsional behavior at the column-slab connection. This enables tracking of the  
10 “unbalanced” moment transferred from the slab to the column. The issue of transferring  
11 moments from the slab to the column through direct shear and eccentricity in shear  
12 deserves careful modeling and design detailing. Section 4.6 of *ATC (2009)* and  
13 *Supplement 1* of *ASCE 41* provide appropriate guidelines.

#### 14 8.5.4.10 Reinforced concrete beam-column joints

15 Bond slip of longitudinal reinforcement in the joint region is best represented in the  
16 models of the beams and columns framing into the joint. A joint model, if employed, is  
17 therefore concerned primarily with the shear force – shear distortion behavior of the joint,  
18 which invites the use of a rotational spring inserted at the joint (Lowes and Altoontash  
19 (2003)). Modified compression field theory has been shown to work well for conforming  
20 joints. Modeling of joint shear behavior is important for joints that are not protected by  
21 capacity design considerations.

22 A more practical approach is to use capacity design criteria to assure that the joint is  
23 stronger than the connected members and to avoid explicit modeling of the joint.  
24 Recommendations for this kind of modeling are given in *ASCE-41 Supplement 1*.

#### 25 8.5.4.11 Reinforced concrete shear walls in bending and shear

26 Fiber and moment – curvature models based on realistic cyclic material models provide  
27 good representations of wall bending behavior over the full height of the wall, with the  
28 exception stated in the next paragraph.

29 Excessive shear deformations should be avoided through capacity design concepts.  
30 Shear behavior is usually decoupled from bending behavior. Coupled models (shear-  
31 flexure-axial) do exist but are difficult to implement at this time. Information on modeling  
32 of flexural and shear strength and stiffness properties of beam-column models and fiber  
33 models are presented in Sections 4.2 and 4.3 of *ATC (2009)*. Most of the models  
34 presented in these sections do not address deterioration due to rebar buckling and  
35 fracture, which necessitates the specification of strain limits to account approximately for  
36 these often critical deterioration modes.

37 In analysis it is often assumed that outside of designated protected regions a shear wall  
38 can be modeled with elastic models. The designation of “protected regions” is usually  
39 made based on elastic design concepts. However, seismic force demands at the MCR  
40 level in tall and slender walls structures depend very much on inelastic redistribution and  
41 higher mode effects, which might lead to large moment and shear force amplifications  
42 compared to values estimated from elastic behavior. Therefore, it is necessary to  
43 perform a comprehensive post-analysis demand/capacity review of the structure in order  
44 to verify that the demands in all protected regions are indeed small enough to justify the

assumption of elastic behavior. The results might disclose the need for re-design or re-analysis.

#### 8.5.4.12 Reinforced concrete coupling beams

New provisions for diagonally reinforced coupling beams are included in *ACI 318-08* that allow two detailing options, one with transverse reinforcement around the groups of diagonal bars and the other with transverse reinforcement around the entire beam. Test results indicate that the load – displacement response for both detailing options are nearly the same.

Recommendations for modeling of coupling beams are presented in Section 4.4 of *ATC (2009)*. This section provides specific modeling data for coupling beams that are flexure controlled, but not for short and stocky coupling beams that are shear controlled. For such coupling beams it appears appropriate to use the modeling parameters listed in Table 6-19 of *ASCE 41*.

Consideration should be given to the phenomenon that walls will “grow” on the tension side due to shifting of the neutral axis, which in turn will increase the vertical deflection at the wall-coupling beam interface and therefore will increase the coupling beam rotation demand.

#### 8.5.4.13 Non-standard components

For components whose design and behavior characteristics are not documented in applicable codes and standards, appropriate design criteria and component models should be developed from analytical and experimental investigations. In general, experimental verification will be necessary for proposed models for inelastic behavior including deterioration. The modeling guidelines of Sections 8.5.1 to 8.5.3 should be considered in the development of analytical models and experimental validation. The models will need approval through the peer review process.

#### 8.5.4.14 Response modification (seismic isolation, damping and energy dissipation) devices

Modeling of response modification devices should be based on data from laboratory tests in which the devices are tested under the severe condition anticipated in a Maximum Considered Earthquake event. The data should come from accredited testing laboratories and the analytical models should be approved by the Structural Peer Review. If there is significant variability in properties of these devices, the structure response predictions should be performed using upper and lower bounds of the properties. If there is a functional limit beyond which the devices cease to operate (e.g., a displacement limit), this functional limit must be represented in the analytical model and it must be demonstrated that the consequences of attaining this limit can be tolerated by the structure. If this cannot be demonstrated, it should be shown that this functional limit will not be attained under 1.5 times the mean demand obtained from Maximum Considered Earthquake response analysis.

#### 8.5.4.15 Foundation modeling

Modeling of the components of the foundation system should follow the same guidelines as outlined for components of the superstructure. Capacity design criteria should be applied to foundation components when feasible. If this cannot be done economically, then inelastic modeling according to the guidelines discussed in Sections 8.5.1 to 8.5.3 will be necessary.

When the foundation-soil interface has a significant effect on the response, it might be necessary to assess the sensitivity of the response to soil properties by varying important soil properties within bounds to be established in consultation with the geotechnical engineer.

**Commentary:** Caution needs to be exercised in designing for, and modeling of, shear and bending in mat foundations. Rigorous analysis will often result in great variations of shear and bending stresses across a mat foundation, whereas it is customary practice to distribute reinforcement uniformly over a large width. This practice might underestimate the importance of local stress distributions close to concentrated loads delivered from core walls. Guidelines are under development by the ACI Task Group on Fixed Foundations

#### 8.5.4.16 Foundation rocking and uplift

Foundation rocking and uplift should be considered as a deformation controlled mode. It does require modeling of the foundation – soil interface through the insertion of springs (or other mechanisms). The orientation and properties of these springs should account for the redistribution of soil stresses and deformations caused by changes in the contact surface between the foundation and the soil and assure transfer of axial and shear forces to the soil. It might be necessary to assess the sensitivity of the response to soil properties by varying important soil properties within bounds to be established in consultation with the geotechnical engineer.

### 8.6 Acceptance criteria at the component level

#### 8.6.1 Force controlled actions

For all actions in components, elements, and connections, in which inelastic deformation capacity cannot be assured through standard or special detailing and that cause a failure mode of severe consequence to structural stability under gravity and lateral loads, the following acceptance criterion applies:

$$F_u \leq \phi F_{n,e}$$

Where

$F_u$  = the demand obtained from nonlinear response history analysis using the smaller of (a) 1.5 times the mean or (b) the mean plus 1.3 times the standard deviation obtained from the individual response history analyses but not less than 1.2 times the mean.

$F_{n,e}$  = nominal strength as computed from applicable material codes but based on expected material properties.

$\phi$  = resistance (strength reduction) factor obtained from applicable material codes.

**Commentary:** Use of the mean value is not believed to be sufficient for non-ductile actions; the use of mean +  $\sigma$  is more appropriate. When less than 20 records are used in nonlinear response history analysis then little confidence can be placed in the computed value of standard deviation. For this reason a default value of 0.5 is used for the coefficient of variation (past studies, e.g., Zareian and Krawinkler (2007) and Yang and Moehle (2008)) have shown that the true

*coefficient of variation due to record to record variability is on the order of 0.4; and some inflation is necessary because of the effect of modeling uncertainties and because there is significant uncertainty in a mean value obtained from seven samples. The limitation of 1.3 times the  $\sigma$  value obtained from maximum considered response analysis is set because for specific cases, such as beam shear in a moment-resisting frame, localized or global mechanisms may limit the force value to a rather stable maximum value and inflation to 1.5 times the mean value may be too large.*

Example actions for which this criterion should be applied include:

- Axial forces in columns (including columns in gravity frames)
- Shear in reinforced concrete beams, columns, shear walls, and diaphragms
- Punching shear in slabs and mat foundations
- Force transfer from diaphragms and collectors to lateral load resisting units
- Connections that are not designed explicitly for the strength of the connected component (e.g., brace connections in braced frames)

For all actions in components, elements, and connections, in which inelastic deformation capacity cannot be assured through standard or special detailing but whose failure will not be of severe consequence to structural stability under gravity and lateral loads, the following acceptance criterion applies:

$$F_u \leq F_{n,e}$$

Where

$F_u$  = the demand obtained from NRHA, using the mean of responses,

$F_{n,e}$  = nominal strength as computed from applicable material codes but based on expected material properties.

Example actions for which this criterion should be applied include:

- Shear in reinforced concrete coupling beams (except for coupling beams with diagonal reinforcement)

#### 8.6.2 Deformation controlled actions

The following criterion is concerned with failure modes associated with relatively slow deterioration. Failure modes leading to rapid deterioration should be prevented through appropriate capacity design and detailing requirements, or should be considered as force controlled actions.

If the ultimate deformation capacity ( $\delta_u$ , see Figure 8.1) is exceeded in any of the response history analyses, the strength associated with this mode of deformation should be assumed as zero and the effects on related strength quantities should be evaluated.

**Commentary:** *An example is ductile fracture in a steel beam that might lead to a loss of bending strength, but might or might inhibit the ability of the beam to transfer shear caused by gravity loads.*

To implement this criterion it is necessary to define the ultimate deformation capacity for each component. This may be done directly (see modeling options 1 to 4 in Section 8.5.3) or indirectly by specifying strain limits in cases in which known but unquantifiable severe deterioration modes exist. For instance, the maximum concrete compressive strain in confined concrete might be limited to 0.015 and the rebar tensile strain might be limited to 0.05 in tension and 0.02 in compression in order to limit the occurrence of rebar buckling and fracture. Chapter 6 of ASCE 41-06 and Chapters 3 and 4 of ATC (2009) provide suitable recommendations for rotation and strain limits for reinforced concrete components.

For steel components the recommendations for rotation limits given in Chapter 5 of ASCE 41 and Chapter 3 of ATC (2009) may be utilized.

## 8.7 Acceptable loss in story strength

In any nonlinear response history analysis, deformation imposed at any story should not result in a loss of total story strength that exceeds 20% of the initial strength.

**Commentary:** Component deterioration will lead to a loss in lateral and gravity load resistance, even if deterioration occurs only in deformation controlled actions. Since no absolute limit is placed on the deformations that can be tolerated in any one component, it is prudent to check that the loss in story resistance does not become excessive. As a general target, the loss in lateral story resistance at maximum drift should not be more than about 20% of the undeteriorated resistance.

## 8.7 Consideration of Uncertainties

There are no specific requirements for incorporation of uncertainties, beyond those pertaining to ground motions (Chapter 5) and the 1.5 factor applied to mean demands (obtained from seven ground motion) in several of the acceptance criteria in Chapter 8.

**Commentary:** The demands obtained for Maximum Considered Earthquake response performance evaluation are intended to be expected values for each of the ground motions used in the analysis. The implication is that expected values are being used to quantify all modeling parameters on which the analytical models of component behavior are based, and that the model indeed represents the cyclic response of each component for the full range of behavior anticipated in the response prediction. There are large uncertainties in estimating some of these component modeling parameters, particularly deformation limits associated with deterioration. The selected deformation limits likely are not mean values, but it is hoped that these guidelines recommend values that are smaller than the true mean and err on the safe side. But there is no assurance of this. Thus, a realistic expectation is that the mean demands obtained from Maximum Considered Earthquake shaking analysis contain cumulative errors resulting from many sources, including modeling and sampling errors, with the latter coming from the fact that a mean obtained from seven samples has an inherent dispersion. And the dispersion of demands around the estimated mean may be very large, and again comes from sampling errors and the dispersion associated with all the modeling parameters.

1        *Unless an engineering performance evaluation is based on concepts that*  
2        *incorporate all these uncertainties explicitly, the confidence in the mean*  
3        *demands obtained from the Maximum Considered Earthquake response*  
4        *analysis is unknown, and the confidence in a measure of dispersion of*  
5        *demands, obtained from seven samples, is low. For this reason no attempt is*  
6        *made here to quantify a measure of dispersion, and a factor of 1.5 is applied to*  
7        *the computed mean demands to provide additional safety against brittle failure*  
8        *modes of severe consequence to structural stability under gravity and lateral*  
9        *loads.*

10  
11



## 9 PRESENTATION OF RESULTS

### 9.1 General

A key element to the successful completion of a Performance Based Design and Peer Review of a tall building is the documentation of the process and the presentation of the results. Key elements of this documentation include the design criteria, the design of the components of the lateral force resisting elements and primary gravity members, the results of the nonlinear response history analyses, and the documentation of the design in the construction documents (primarily drawings and specifications). Defining the scope and details of the results to be presented to reviewers as completely as possible at the beginning of the peer review will help to align the expectations of the various participants, and lessen the chance of significant re-work by the design team. This alignment of expectations and follow through by the design team and reviewers throughout the various phase of the project will require commitment of all parties.

The scope and detail of each presentation of information developed by the design team for review will be directly related to the phase of the project, moving from the global to the specific as the design advances from concepts to final design. At all steps in the process, highlight all assumptions that are significant to the building response, or which may be outside of widely accepted standard practice or procedures, and/or otherwise controversial for specific review and comment by reviewers. State assumptions clearly together with discussion of the potential implications of their implementation.

Present documentation in a way that facilitates the efficient transfer of information to the reviewers. Interpretation of the results and validation of assumptions and design criteria are key elements in an effective presentation of results. More is not necessarily better, since nonlinear dynamic analyses generate so much raw response data. For example, presenting graphical results of key maximum response components with explanations of "what it means" is far more effective than submitting binders (or CD's) full of raw analysis data. In addition, all spreadsheets key to the structural analysis or design should be accompanied by a fully worked out example to explain the spreadsheet operations.

Another item that needs to be discussed and understood is the intended construction phasing. If an early excavation/foundation package is anticipated, this should be discussed to determine how it will impact the design and review process.

### 9.2 Design Criteria

The first, and in many ways most critical document in the process is the Design Criteria. The Design Criteria is the key element in describing the design intent, primary assumptions, analyses to be performed, acceptance criteria, etc. Once agreed to by all participants, the Design Criteria becomes the rules to which subsequent design and analyses are checked. Complete and clear documentation of this document will help avoid misunderstandings later in the process, and the potential for expensive re-work and delayed progress. Generally, the more detail included in the document, especially as related to material response and acceptance criteria assumptions, the greater the

chance for an efficient presentation and review process. Refer to Section 4 for a recommended outline of Design Criteria contents.

### **9.3 Geotechnical/Seismic Ground Motion Report**

The other document of importance to be developed and reviewed in the early stages of the project is the Geotechnical/Ground Motion Report. The geotechnical portion of the report, which provides design parameters for foundation elements, information on groundwater, retaining wall design pressures, etc., is basically the same as that required for any significant design project. One item that may be included in the report that is beyond the typical scope could be stiffness and nonlinear displacement quantities of supporting soils that can be incorporated into the building analysis model.

A properly documented ground motion report for a tall building design project is extremely important to the success of the design process. There is continuing debate over the validity and appropriateness of many significant recent and ongoing developments in the procedures used in the generation of response histories for nonlinear analyses. These issues may be especially contentious for Maximum Considered Earthquake shaking levels in the long period range of interest in tall building design, resulting in the need for extensive description of the assumptions and process followed. Spectral matching, scaling processes, use of recently developed attenuation procedures, near field and directivity effects, hazard disaggregation, etc., all can have significant impact on the suite of response histories to be generated for use in the structural analyses. Whenever possible, it is recommended that acceleration, velocity and displacement traces be presented for each of the proposed response histories. This is especially important when spectral matching approaches with large scaling factors are used to generate Maximum Considered Earthquake ground motions.

Refer to Section 5 for further details on the procedures to be followed and recommended contents of the Ground Motion report. Summarize this report in the Design Criteria Document, and included it in complete form as an Appendix to the Design Criteria.

### **9.4 Preliminary/Conceptual Design**

The preliminary/conceptual design package should include a design narrative of structural system, which is likely similar to, but more fully developed than that presented in the Design Criteria Document. Present drawings for both gravity and lateral force resisting systems, including preliminary member sizes, wall thicknesses, etc. Provide proposed detailing approaches for ductile elements of lateral system. Note special force transfers (e.g. at podium and outrigger levels), and approach to design of these elements, including sample design calculations and preliminary detailing concepts. If damping or energy dissipation elements are to be incorporated, describe assumptions used in their initial design. Provide outline specifications for structural sections, highlighting material requirements that are unusual. Provide initial design calculations used to develop member sizes including member stiffness assumptions, period calculations, base shear capacity, etc. If full building model has been developed, present model input and basic results (base shear, overturning moment, interstory drift plots, etc.).

## **9.5 Service Level Evaluation**

Provide executive summary discussion. Re-state response spectrum for this evaluation. Provide input model with description of elements and modeling assumptions. Present time history plots for acceleration, velocity and displacement. All demand/capacity ratios that exceed a value of 1.0 should be clearly described. Provide information needed to compare model with design drawings. Provide capacity design calculations for major structural elements. Present base shear results. Provide interstory drift plots and comparison to design criteria limits. Provide maximum D/C ratios for major structural elements. Discuss any elements that may exceed drift or capacity limits. Note torsional response, if significant. Discuss level of dispersion of major response quantities. Verify that results are consistent with Design Criteria Document.

## **9.6 Collapse Level Evaluation.**

Provide executive summary discussion. Re-state response spectrum for this evaluation. Provide input model with description of elements and modeling assumptions. Present time history plots for acceleration, velocity and displacement. Provide detailed description of nonlinear element modeling, with clear and complete discussion of assumptions. Provide information needed to compare model with design drawings. Provide capacity design calculations (both force and deformation) for major structural elements. Compare critical element deformation demands to capacity limits. Present base shear and overturning moment results. Provide interstory drift plots and comparison to design criteria limits. Discuss any elements that may exceed drift or capacity limits. If special elements (outriggers, damping or energy dissipation elements, e.g.) are included in the design, provide a separate discussion of the response of these elements. Include evaluation of foundation elements and major force transfer elements/levels, such as the podium and outriggers.

Refer to previous discussion in Section 8 for other items as appropriate.

## **9.7 Sample Table of Contents for Design Submittals (See Appendix XX)**

Appendix A provides a sample table of contents for the presentation of analysis and design results. The appendix is formulated for a concrete shear wall lateral system. Similar contents would be expected for other lateral systems. This Table of Contents addresses a project with an early excavation/foundation project, which are commonplace on many tall buildings.

This table can be used as a starting point for discussion between the design team and the Structural Peer Review for the submittal requirements to be mutually agreed to for the project at hand.

## 10 PROJECT REVIEW

### 10.1 General

Because of the complexity of the analyses used to demonstrate building performance (which typically explicitly include nonlinear response effects), most building departments have initiated a requirement for independent peer review when designs are submitted for permit under the alternative means and methods clause. The composition of the peer review is typically jointly determined by the owner/design team and the building department. More members of the peer review team may be added as appropriate to fully address the special features of the proposed project. In general, the peer reviewers should jointly possess expertise in geotechnical engineering and seismic hazards, seismic performance of structures as a whole, as well as structures with elements of the type employed and structural design of tall buildings.

The peer review process should initiate as early in the design process as possible. Early agreement and discussion of the fundamental design decisions, assumptions and approaches will help avoid re-work later in the design process that will impact both the project cost and schedule. With projects of the size and complexity of typical tall buildings, there may be differences of opinion on various issues during the process that need to be negotiated between the parties. The earlier in the process that these issues can be identified and resolved, the less effect that they will ultimately have on the building cost and design/construction schedule. Early participation by the peer reviewer should also help to establish a good working relationship with the design team.

It should be noted that the existence of a peer review on a project does not relieve the engineer of record from any of their design responsibility. However, because of the level of complexity incorporated in tall building design, in many cases it is recognized that review of these elements of the design effectively constitutes the plan review of the seismic system (even though contracts may say that this is not the case). Peer review participation is not intended to replace quality assurance measures ordinarily exercised by the engineer of record. Responsibility for the structural design remains solely with the engineer of record, as does the burden to demonstrate conformance of the structural design to the intent of the design criteria document. The responsibility for conducting plan review resides with the building official.

The scope of peer review comments should begin with broad, general issues, and progressively move toward the more detailed. It is generally not fair to the engineer of record to bring up new general issues at later stages of the design.

Proper documentation of the peer review process is important for incorporation into the project records. It is best to develop a systematic process for establishing, tracking, and resolving comments generated by the peer review. In many cases, this takes on the form of a written spreadsheet that logs all the comments and resolutions, with dates attached. Comments that are discussed and/or any resolutions that are reached during project review meetings or conference calls should be formally written into project review comment spreadsheet.

The timing of reviews should be incorporated into the project design schedule so that they minimize any impact on the schedule. Periods of both review and response by the design team should be included into the project design schedule.

## **10.2 Reviewer Qualifications**

On many projects peer review is provided by a review team, often comprising 3 persons. The first is typically an expert in the generation of site specific ground motions and accelerograms for use in the nonlinear analyses; geotechnical engineering or geological engineering. The second is often a practicing structural engineer that is felt to have the expertise needed to properly review the proposed structural system, with experience in structural engineering, performance-based earthquake engineering, nonlinear response history analysis, and tall building design. This engineer's supporting staff is often performs detailed reviews of analytical models. The final person on many panels is often a Professor of structural engineering with research experience and expertise in the proposed structural system, and expertise in structural engineering, earthquake engineering research, performance-based earthquake engineering, nonlinear response history analysis, tall building design. There is no requirement that a panel be comprised of 3 members. The number of members may be expanded or contracted as appropriate, however, the reviewer(s) as a whole, should possess expertise in all of the areas noted above.

Selection of reviewers is often a joint effort of the building official and the owner/design team. It is important for the selection process to obtain reviewers that have both the proper background and expertise to perform the peer review, and also the time available to commit to help the process proceed in a timely manner. Reviewers should not bear a conflict of interest with respect to the project and should not be part of the project design team. The reviewers provide their professional opinion to and act under the instructions of the Building Official.

When review is performed by a team, one team member should serve as the review team chair and should be responsible for mediating disputes between the reviewers and the engineer of record, and for expressing the official positions and opinions of the review team. The review team chair should be a structural engineer licensed to practice in the jurisdiction in which the structure is to be constructed.

## **10.3 Scope**

It is important to have a clear definition of the scope of the peer review. The building official should define the minimum acceptable scope. In most cases, the review is limited to the seismic design, even though design for wind forces and deformations (specifically drift limits for serviceability and occupant comfort) may control the design of many tall buildings. The design of gravity load resisting elements is typically excluded as well, except when deformation compatibility issues need to be checked. Nonstructural elements that can create hazards to life safety are often included to ensure that proper anchorage and/or deformation control has been provided.

Based on the scope of review identified by the building official, the reviewers, either individually or as a team, should develop a written scope of work in their contract to provide engineering services. The scope of services should include review of the following: earthquake hazard determination, ground motion characterizations, seismic design methodology, seismic performance goals, acceptance criteria, mathematical modeling and simulation, seismic design and results, drawings and specifications.

**Commentary:** *At the discretion of the building official, as well as other members of the development team, the scope of review may be expanded to include review of other building aspects, including wind design and critical non-structural elements.*

Convened review as early in the structural design phase as practicable to afford the reviewers opportunity to evaluate fundamental design decisions that could disrupt design development if addressed later in the design phase. Early in the design phase, the engineer of record, the building official, and the reviewers should jointly establish the frequency and timing of review milestones, and the degree to which the engineer of record anticipates the design will be developed for each milestone.

Reviewers should provide written comments to the engineer of record and to the building official. The engineer of record should provide written responses to review comments, with multiple rounds of comment/response sometimes needed for key issues. A log should be jointly maintained by the engineer of record and the reviewers, summarizing all comments, responses to comments, and resolutions. At the conclusion of the review, the reviewers should submit a written report to the building official documenting the scope of the review, the comment log, and indicating the reviewers' professional opinion regarding the design's general conformance to the requirements of the design criteria document. The building official may request interim reports from the reviewers at the time of interim permit reviews.

**Commentary:** *None of the reports or documents from the review is Construction Documents. Under no circumstances should letters or other documents from the review be put into the project drawings or reproduced in any other way that makes review documents appear to be part of the Construction Contract Documents. The engineer of record is solely responsible for the Construction Contract Documents. Documents from the reviewers should be retained as part of the building department project files.*

#### 10.4 Dispute Resolution

Given the complexity of tall buildings and the performance-based analyses being performed, it is not uncommon for disagreements to arise between the engineer of record and the reviewers. Generally, these disagreements fall into one of two categories. The first is regarding the level of complexity of analysis/evaluation that has been performed to validate an aspect of the design. In most cases, this should be resolvable with additional analyses, confirming studies, etc. The second case is related to differences of opinion in the interpretation of results, specifically as to whether or not elements of the design criteria have been met. Resolution of such issues may be obtained through sensitivity analyses, bounding analyses or other means.

If cases arise where disputes between the engineer of record and reviewers are not resolved, the building official is required to "break the tie". The building official can do so based on their knowledge of the situation, or in some cases, may retain other experts to review the material and generate a recommended course of action.

For jurisdictions that have a significant number of tall building projects incorporating performance based design procedures, establishment of an advisory board should be considered. Such an advisory board should consist of experts that are widely respected and recognized for their expertise in relevant fields, including but not limited to, structural engineering, performance-based design, nonlinear analysis techniques, and geotechnical engineering. The advisory board members may be elected to serve for a predetermined period of time on a staggered basis. The advisory board should oversee the design review process across multiple projects periodically; assist the Building Official in developing criteria and procedures spanning similar design conditions, and resolve disputes arising under peer review.

#### **10.5 Post-review Revision**

Because of the fast track nature of many modern large building projects, it should be expected that significant changes to the design may occur during the final stages of design and/or the construction phase. In this event, the engineer of record should inform the building official, describing the changes to the structural design, detailing, or materials made subsequent to the completion of peer review. At the discretion of the building official, such changes may be subject to additional reviewed by the peer review team and approved by the building official.

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## APPENDIX A

### SUGGESTED CONTENTS OF REVIEW SUBMITTALS

The following is a suggested starting point for a table of contents to be submitted for the purpose of obtaining approval by the peer review for tall building projects. This table of contents assumes that a shear wall system with a mat foundation is the primary lateral force resisting system. If moment frames or another foundation system are being used, force and deformation demand checks similar to those listed below should be provided. This list also addresses a building with outrigger levels, which may be deleted if the building does not incorporate such elements into the structural system.

Since many projects of this type have a phased review and approval that often includes a foundation package, the items that are in **BOLD and Underlined** are anticipated to be submitted for a submittal for a **foundation** permit. They should also be submitted as part of a complete permit application package.

The list that follows is intended to be used as a starting point for discussion between the design team and the peer review panel. It is expected that the final determination of information to be submitted for review will vary depending on the individual characteristics of the project at hand.

#### 1.0 **General Information**

##### 1.1 **Basis of Design Document, to include at a minimum:**

- **Project scope**
- **Description of structural system**
- **Governing building codes and references**
- **Material List**
- **Seismic design description/objective/overall approach**
- **Code exceptions**
- **Design enhancements (items considered to be above code minimums for improved performance or other reasons)**
- **Load combinations**

##### 1.1 **Geotechnical Report**

- **Final Ground Motion Study**
- **General Soil Design Parameters**

##### 1.2 **Wind Tunnel Report**

- **Acceleration Study**
- **Cladding Study**
- **Main Wind Force Resisting System Study (Loads)**

#### 2.0 **Gravity System Design**

##### 2.1 **Description of Gravity Framing System**

- **Dead and Live Load Maps**
- **Floor Framing Maps**
- **Column Loads Summary and Design**
- **Tower Level Slab Design**
- **Podium Level Slab Design**
- **Parking Level Slab Design**
- **Gravity Column Design**
- **Mat and Isolated Spread Footing Design**

**3.0 ServiceLevel (SL) Evaluation**

**3.1 Executive Summary of Design approach for Serviceability and Goal of Design**

- R values used
- Redundancy considerations
- Torsion considerations
- Load Combinations Used

**3.2 Service Level Response Spectrum (using return period agreed to in Design Criteria)**

**3.3 Building Mass Analysis – approach for mass eccentricity**

**3.4 Lateral Distribution of forces – Base Shear Scaling**

**3.5 Linear Elastic Models**

- Model Descriptions
- General statement about performance of model (stability, mode shapes, behavior, displacements, force distribution)
- Base Shear Summary Table
- Confirmation of drift limit within design criteria
- Summary stress checks (C/D ratios)

**3.6 Shear Wall Strength Analysis**

- Description of Design Process
- Sample Wall Strength calculation
- Summary of Wall strength calculations
- Shear wall Details

**4.0 Maximum Considered Response Level (MCRL)Evaluation**

**4.1 Executive Summary of Design approach for Maximum Considered Response Level and Goal of Design**

- Non-linear properties used
- Acceptance Criteria used for elements
- Table of values used (mean, mean+sigma) vs acceptable limit of response.
- Torsion considerations
- Ground Motions used
- Record truncation summary table.
- Load Combinations Used

**4.2 MCRL Response Spectrum**

- Scale Ground Motion Response Spectra

**4.3 Building Mass Analysis – include approach for mass eccentricity as appropriate**

**4.4 Non-Linear Models**

- Model Descriptions
- General statement about performance of model (stability, mode shapes, behavior, displacements, force distribution)
- Development of Non-Linear Model
- Model assumptions for the backstay conditions at podium levels
- Modal Periods Summary
- Sample Mode shape Plots
- Base Shear Summary Chart/Table

**4.5 Global/General Response Results**

- Story Drift Plots, Confirmation of elastic element response, local demands (deformation primarily) on key nonlinear elements, outrigger response, etc.

- 4.6 Redundancy Verification
  - Statement of comparison of building component responses with varying properties across the building.
- 4.7 **Shear Wall Yielding Verification**
  - Statement of Performance expectation of walls
  - Curvature/Strain acceptance criteria
  - Description of modeling approach
  - Description of wall response
  - Demand value used (mean value)
  - Curvature/Strain Response plot vs Acceptance Criteria (for controlling time histories)
- 4.8 **Boundary Element Design**
  - Statement of Performance expectation of Boundary Elements
  - Acceptance criteria of boundary Elements
  - Description of Modeling Approach
  - Sample Boundary Element capacity design calculation
  - Description of Boundary Element response
  - Demand Value Used (Mean+sigma)
  - Boundary Element Response Plots
- 4.9 **Link Beam Design**
  - Statement of Performance expectation of Link Beam elements
  - Rotation at Link Beam connections
  - Description of design basis
  - Description of Modeling Approach
  - Shear Hinge Properties of Link Beam over Openings
  - Properties of Link Beams at connections to Wall Boundary Elements
  - Description of Link Beam response
  - Demand Value Used (Mean Value)
  - Shear Link response plots
  - Strength section checks for elastic sections
- 4.10 Outrigger Verification
  - Statement of Performance expectation of Outriggers
  - Elastic Section properties
  - Rotation hinges at connections
  - Buckling Restrained Brace/Damper yielding
  - 4.10.1 Description of modeling approach for Outrigger elements
    - BRB/Damper modeling
    - Moment Hinge locations
  - 4.10.2 Description of Outrigger response
    - Demand value used (mean value)
  - 4.10.3 Verification of Outrigger trusses Truss Elevation indicating non-linear elements
    - BRB/Damper response plots (tension yielding)
    - Strength section checks
    - 4.10.3.1 Roof Truss Elevations (if any) indicating non-linear elements
      - BRB/damper response plots (tension yielding)
      - Strength section checks
- 4.11 Diaphragm/Drum Design

- Description of Diaphragm and drag element design methods
  - Diaphragm inertial force distribution table
  - Sample Diaphragm Verification Calculation
  - Sample Drag Verification Calculation
  - Summary Verification calculations for Diaphragms and Drags on remaining Tower floors
  - Diaphragm verification of Podium Slab(s).
  - Description of podium force transfer modeling approach
    - Include sketches to describe intended load paths
  - Linear force distribution
  - Modified force distribution (if any)
  - Strut-Tie models (if any)
  - Reinforcing layout, including chords, collectors, typical steel, etc.
- 5.0 Foundation Design**
- 5.1 Summary narrative of design approach for Mat Foundation including which level evaluation (MCRL/SL) various components of the mat are being designed to including:**
- Shear stress limits (MCRL and SL)
  - Design for Flexure (MCRL and SL)
  - Design for punching shear (MCRL)
  - Design for Beam Shear (MCRL and SL)
  - Soil Bearing (MCRL and SL)
- 5.2 Geotechnical design information for mat**
- Soil springs
  - Calculation of soil springs for building analysis model
  - Bearing pressures
  - Anticipated settlements
- 5.3 Narrative of Force distribution to mat**
- Gravity loads
  - Wind Loads
  - Seismic load
  - MCRL and SL
  - Modal Based force for sign convention
- 5.4 Design of Mat**
- Flexural Design Calculations
    - Analysis results
    - Reinforcing plots
  - Punching shear Calculations
    - Sample punching shear calculation
    - Summary of punching shear calculations (spreadsheet)
  - Beam shear calculations
    - Sample beam shear calculations
    - Summary of beam shear calculations (spreadsheet)
  - Mat Bearing pressures
  - Contour Plot of bearing pressures for Gravity Loads only
  - Contour Plot of bearing pressures for Gravity+Seismic loads
  - Contour Plot of bearing pressures for Gravity+Wind Loads
  - Design of Boundary Element embeds into mat foundation
    - Design assumptions used for SL , MCRL evaluations, and Wind design loads

- **Sample Calculation of embed calculations**
- **Summary Calculation of embeds**
- **Detail of Embed into mat**
- 5.5 Design of foundations of outrigger columns**
- 5.6 Determination of mat design forces generated by basement walls (from 5.7 below)**
- 5.7 Basement Walls Design
  - Description of lateral forces used for design of the basement walls
    - SL evaluation forces
    - MCRL evaluation forces
  - Force distribution plots
  - Sample calculation of wall shear and bending
- 5.8 Isolated spread footing design beyond the footprint of the tower
- 5.9 Miscellaneous design elements